# On bracket polynomials for Alexander type invariants

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#### Abstract

The bracket polynomial is not only a fundamental tool for defining the Jones polynomial but also provides an elementary proof of its invariance. In contrast, although the Alexander polynomial is a classical link invariant as important as the Jones polynomial, no bracket polynomial has been defined for it, and no elementary proof of its invariance using link diagrams has been given. In this paper, we introduce a bracket polynomial for the (multivariable) Alexander polynomial, providing an elementary proof of its invariance. Furthermore, we extend this framework by defining a quandle-twisted version of the bracket polynomial. We demonstrate that this new polynomial serves as a bracket polynomial for the quandle-twisted Alexander invariant is a generalization of the Alexander polynomial, the multivariable Alexander polynomial and the twisted Alexander polynomial.

## 1 Introduction

The Alexander–Conway polynomial [1, 2] and the Jones polynomial [9] are well-known knot invariants and are easily calculated with their skein relations. The Kauffman bracket [11] gives an elementary proof of the invariance of the Jones polynomial. In this paper, we introduce counterparts of the Kauffman bracket for the Alexander–Conway polynomial and the multivariable Alexander polynomial and give elementary proofs of their invariance. We also extend the definitions of the bracket polynomials to a quandle twisted Alexander invariant with  $f_1 + f_2 = 1$ . A quandle twisted Alexander invariant [7] is a family of invariants constructed by fixing a quandle and its linear extension. We note that a bracket polynomial for the HOMFLYPT polynomial [3, 16] was given in [14]. Our bracket polynomials are for Alexander type invariants. We focus on bracket polynomials for the Alexander–Conway polynomial, the multivariable Alexander polynomial and the  $R_p$ -twisted Alexander polynomial and give their properties.

In Section 2, we describe the behavior of the bracket polynomial for the Alexander–Conway polynomial under the Reidemeister moves and show that its normalization coincides with the Alexander–Conway polynomial, which gives an elementary proof of the invariance of the Alexander–Conway polynomial. We establish the same result for the multivariable Alexander polynomial and prove it in Section 5. In Section 3, we recall the notions of a quandle [10, 13], an Alexander pair [6], a column relation map [5] and a row relation map [4]. A quandle is an algebraic structure whose axioms correspond to the Reidemeister moves on link diagrams. The others are notions used to define a quandle twisted Alexander invariant, which is a generalization of the Alexander–Conway polynomial, the multivariable Alexander polynomial and the twisted Alexander polynomial [12, 17]. A quandle twisted Alexander matrix is defined with an Alexander pair  $(f_1, f_2)$ , which is a pair of maps corresponding to a linear extension of a quandle. A row relation map and a column relation map also yield matrices which annihilate the quandle twisted Alexander matrix from the left and right, respectively. We recall the definition of the quandle twisted Alexander invariant in Section 6. We introduce a quandle twisted version of the bracket polynomial in Section 4 and show that the bracket polynomial coincides with the determinant of a generalized quandle twisted Alexander matrix of a diagram with vertices in Section 7. We show that the  $R_p$ -twisted Alexander invariant is recoverable from the quandle twisted version of the bracket polynomial in Section 8 and give some properties of the invariant in Section 9.

In the rest of this section, we provide an overview of the results of this paper with minimal introduction of terminology. See Sections 2, 3 and 6 for the precise definitions of unfamiliar terms. Throughout this paper we work in the piecewise linear category.

An (n, n)-tangle is a tangle with n top endpoints and n bottom endpoints as depicted in the left picture of Figure 1. In this paper, a tangle may contain vertices other than endpoints. We call such vertices *inner vertices*. Throughout this paper, we assume that an inner vertex is of indegree 1 and of degree 1, 2 or 3. A tangle is *classical* if it has no inner vertices. In this paper, a graph and a tangle may contain circle components, which have no vertices. In particular, a (0,0)-tangle is a link. We denote by  $\hat{T}$  the closure of an (n,n)-tangle T (see Figure 1). For a diagram D of T, we denote by  $\hat{D}$ the diagram of  $\hat{T}$  as depicted in Figure 1. A tangle is *cyclic* if its underlying graph contains a cycle. A tangle is *acyclic* if it is not cyclic, that is, its



Figure 1: An (n, n)-tangle and its closure

underlying graph is a disjoint union of trees.

**Definition 1.1.** Let D be a diagram of an oriented uni-trivalent (n, n)-tangle. We define  $\langle D \rangle \in \mathbb{Z}[t^{\pm 1}]$  by the local relations

and, for a diagram D without crossings,

 $\langle D \rangle = \begin{cases} 1 & \text{if } D \text{ is a diagram of an acyclic tangle,} \\ 0 & \text{if } D \text{ is a diagram of a cyclic tangle.} \end{cases}$ 

Let T be an oriented classical (n, n)-tangle, and let D be a diagram of T. We define the *rotation number* rot(D) of D to be the total rotation angle of the tangent vector on D divided by  $2\pi$ . The *writhe* wr(D) of D is the total number of positive crossings minus the total number of negative crossings of D. We then have  $rot(D) = rot(\widehat{D}) - n$  and  $wr(D) = wr(\widehat{D})$ .

**Theorem 1.2.** Let T be an oriented classical (n, n)-tangle. Let D be a diagram of T. Then

$$t^{\frac{\operatorname{rot}(D) + \operatorname{wr}(D)}{2}}\langle D \rangle$$

is invariant under the Reidemeister moves. In particular, for an oriented classical (1, 1)-tangle T, we have

$$\Delta_{\widehat{T}}(t) = t^{\frac{\operatorname{rot}(D) + \operatorname{wr}(D)}{2}} \langle D \rangle,$$

where  $\Delta_L(t)$  is the Alexander-Conway polynomial of an oriented link L.

Let T be an oriented (n, n)-tangle, and let  $K_1, \ldots, K_r$  be the connected components of T. Let D be a diagram of T. We denote by  $\mathcal{A}(D)$  the set of arcs of D, where an arc of D is a piece of a curve each of whose endpoints is an undercrossing or a vertex. Suppose that T is classical. We denote by  $\mathcal{A}(D; K_i)$  the set of arcs of D that originate from  $K_i$ , and denote by  $C(D; K_i)$ the set of crossings of D whose under arcs originate from  $K_i$ . We define  $\operatorname{wr}(D; K_i) := \sum_{c \in C(D; K_i)} \operatorname{sgn}(c)$ . We then have  $\operatorname{wr}(D) = \sum_{i=1}^r \operatorname{wr}(D; K_i)$ .

**Definition 1.3.** Let D be a diagram of an oriented 1, 2, 3-valent (n, n)-tangle T, and let  $\rho : \mathcal{A}(D) \to \mathbb{Z}_{>0}$  be a map. We define  $\langle (D, \rho) \rangle \in \mathbb{Z}[t_1^{\pm 1}, t_2^{\pm 1}, \ldots]$  by the local relations

and, for a diagram D without crossings,

 $\langle (D, \rho) \rangle = \begin{cases} 1 & \text{if } D \text{ is a diagram of an acyclic tangle,} \\ 0 & \text{if } D \text{ is a diagram of a cyclic tangle.} \end{cases}$ 

A colored classical (n, n)-tangle is a pair  $(T, \rho)$  of a classical (n, n)-tangle T and a map  $\rho : \{K_1, \ldots, K_r\} \to \mathbb{Z}_{>0}$ , where  $K_1, \ldots, K_r$  are the connected components of T. An ordered classical (n, n)-tangle is a colored classical (n, n)-tangle  $(T, \rho)$  such that  $\rho(K_i) = i$  for any  $i \in \{1, \ldots, r\}$ . We often write  $T = T_1 \cup \cdots \cup T_r$  for an ordered classical (n, n)-tangle  $(T, \rho)$  by omitting  $\rho$ . The multivariable Alexander polynomial  $\Delta_L(t_1, \ldots, t_r)$  is an invariant of an ordered oriented link  $L = K_1 \cup \cdots \cup K_r$ . Let D be a diagram of T. A map  $\rho : \{K_1, \ldots, K_r\} \to \mathbb{Z}_{>0}$  induces a map from  $\mathcal{A}(D)$  to  $\mathbb{Z}_{>0}$  which sends  $\alpha \in \mathcal{A}(D; K_i)$  into  $\rho(K_i)$ . We denote the map by the same symbol  $\rho : \mathcal{A}(D) \to \mathbb{Z}_{>0}$ .

**Theorem 1.4.** Let  $(T, \rho)$  be a colored oriented classical (n, n)-tangle, and let D be a diagram of T. Let  $K_1, \ldots, K_r$  be the connected components of T. Then

$$\prod_{i=1}^{r} t_{\rho(K_{i})}^{\frac{\operatorname{rot}(D(K_{i})) + \operatorname{wr}(D;K_{i})}{2}} \langle (D, \rho) \rangle$$

is invariant under the colored Reidemeister moves. In particular, for an ordered oriented classical (1,1)-tangle  $T = T_1 \cup \cdots \cup T_r$  such that  $T_j$  is a strand connecting the end points of T, we have

$$\Delta_{\widehat{T}}(t_1,\ldots,t_r) = \frac{\prod_{i=1}^r t_i^{\frac{\operatorname{rot}(D(K_i)) + \operatorname{wr}(D;K_i)}{2}} \langle (D,\rho) \rangle}{t_j^{1/2} - t_j^{-1/2}}$$

Let  $R_p = (\mathbb{Z}/p\mathbb{Z}, \triangleleft)$  be the dihedral quandle of order p, where the binary operation is given by  $a \triangleleft b = 2b - a$ .

**Definition 1.5.** Let p be an odd prime number, and let  $F := \mathbb{Q}(\sqrt{-1})[t]/(t^{p-1} + \cdots + 1)$ . Let D be a diagram of an oriented 1, 2, 3-valent (n, n)-tangle T, and let  $\rho : \mathcal{A}(D) \to R_p$  be a map. We define  $\langle (D, \rho) \rangle \in F$  by the local relations

$$\begin{pmatrix} a \\ b \\ c \end{pmatrix} = t^{b-a} \begin{pmatrix} a \\ b \end{pmatrix} \begin{pmatrix} b \\ c \end{pmatrix} + \begin{pmatrix} a \\ b \\ c \end{pmatrix} \begin{pmatrix} b \\ c \end{pmatrix} - t^{b-a} \begin{pmatrix} a \\ b \\ c \end{pmatrix} \begin{pmatrix} b \\ c \\ c \end{pmatrix} ,$$

$$\begin{pmatrix} b \\ a \\ b \end{pmatrix} \begin{pmatrix} c \\ c \\ b \end{pmatrix} = t^{a-b} \begin{pmatrix} b \\ a \end{pmatrix} \begin{pmatrix} c \\ b \end{pmatrix} - t^{a-b} \begin{pmatrix} b \\ a \\ c \end{pmatrix} + \begin{pmatrix} b \\ a \\ c \end{pmatrix} + \begin{pmatrix} b \\ a \\ c \end{pmatrix} ,$$

and, for a diagram D without crossings,

$$\langle (D, \rho) \rangle = \begin{cases} 1 & \text{if } D \text{ is a diagram of an acyclic tangle,} \\ 0 & \text{if } D \text{ is a diagram of a cyclic tangle.} \end{cases}$$

We denote by Q(L) the fundamental quandle of an oriented link L. Let Q be a quandle. A quandle representation  $\rho: Q(L) \to Q$  induces an Q-coloring of a diagram D of L, which we denote by the same symbol  $\rho: \mathcal{A}(D) \to Q$ . We also use the same symbol  $\rho: \mathcal{A}(D') \to Q$  for the restriction of the Q-coloring  $\rho: \mathcal{A}(D) \to Q$  to a subdiagram D' of D, which is a part of D.

Let L be an oriented link, and let  $\rho: Q(L) \to R_p$  be a quandle representation. Suppose  $\rho$  is trivial. Let  $D_1$  be a diagram of a (1, 1)-tangle whose closure is L. Suppose  $\rho$  is nontrivial. Let  $D_2$  be a diagram of a (2, 2)-tangle whose closure is L such that the images of  $\rho$  on the top endpoints of  $D_2$  are distinct elements  $a, b \in R_p$ . We then define

$$\Delta_{p}(L,\rho) := \begin{cases} (-1)^{-\frac{\operatorname{rot}(D_{1}) + \operatorname{wr}(D_{1})}{2}} \langle (D_{1},\rho) \rangle & \text{ if } \rho \text{ is trivial,} \\ \\ \frac{(-1)^{-\frac{\operatorname{rot}(D_{2}) + \operatorname{wr}(D_{2})}{2}} \langle (D_{2},\rho) \rangle}{(t^{a} - t^{b})(t^{-a} - t^{-b})} & \text{ if } \rho \text{ is nontrivial.} \end{cases}$$

**Theorem 1.6.** Let T be an oriented classical (n, n)-tangle, and let D be a diagram of T. Let  $\rho : \mathcal{A}(D) \to R_p$  be a quandle coloring. Then

$$(-1)^{-\frac{\operatorname{rot}(D)+\operatorname{wr}(D)}{2}}\langle (D,\rho)\rangle$$

is invariant under the colored Reidemeister moves. Furthermore, for an oriented r-component link  $L = K_1 \cup \cdots \cup K_r$  and its quandle representation  $\rho: Q(L) \to R_p$ , we have

$$\Delta_p(L,\rho) = (-1)^{r-1} \Delta_L(-1)$$

if  $\rho$  is trivial, and we have

$$\Delta_p(L,\rho) = (-1)^{r/2 + \mathrm{lk}(L)} (t - 2 + t^{-1}) \Delta(L,\rho; f_1, f_2; 0, 1)$$

if  $\rho$  is nontrivial, where  $lk(L) := \sum_{i < j} lk(K_i, K_j)$  and  $\Delta(L, \rho; f_1, f_2; 0, 1)$  is the normalized quandle twisted Alexander invariant with  $f_1(a, b) = -t^{b-a}$  and  $f_2(a, b) = t^{b-a} + 1$ .

Proposition 1.7. We have

$$\Delta_{p} \begin{pmatrix} a & b \\ \vdots & b \\ a & b \end{pmatrix} p = (-1)^{-p/2} \Delta_{p} \begin{pmatrix} a \\ a \\ b \\ b \end{pmatrix},$$

$$\Delta_{p} \begin{pmatrix} a & b \\ \vdots & a \\ \vdots & a \end{pmatrix} n = (-1)^{(1-n)/2} n \Delta_{p} \begin{pmatrix} a \\ a \\ a \\ a \end{pmatrix} + (-1)^{-n/2} (1-n) \Delta_{p} \begin{pmatrix} a \\ a \\ a \end{pmatrix} \begin{pmatrix} a \\ a \\ a \end{pmatrix}$$

for  $n \in \mathbb{Z}$  and any distinct elements  $a, b \in R_p$ , where the *n* crossings indicates -n negative crossings if n < 0. We have

$$\Delta_p \left( \bigodot^a \right) = 1,$$

$$\Delta_p \left( \bigcirc^a \bigoplus^b \right) = \begin{cases} \frac{1}{(t^a - t^b)(t^{-a} - t^{-b})} & \text{if } a \neq b, \\ 0 & \text{if } a = b, \end{cases}$$

$$\Delta_p \left( \bigcirc^a \bigoplus^a \bigoplus^a \right) = 0$$

for  $r \geq 3$  and  $a, b, a_1 \dots, a_r \in R_p$ .

Using the properties in Proposition 1.7, we have the following calculation example.

**Example 1.8.** For  $a, b, c \in R_p$ , we have

$$\Delta_{p}\left(\underbrace{a \atop b \atop c}_{b} \begin{array}{c} (a \neq b \neq c), \\ (a \neq b \neq c), \\ (a \neq b = c), \\ (a = b \neq c), \\ p^{2} \\ (a = b = c), \\ p^{2} \\ (a \neq b \neq c), \\ p^{2} \\ (a \neq b \neq c), \\ (a \neq b \neq c)$$

We remark that these two knots are generalization of the granny knot and square knot and can be distinguished by the invariant  $\Delta_p$ .

# 2 A bracket polynomial for the Alexander– Conway polynomial

A *tangle* is a graph embedded in  $I^3$  such that the intersection of the graph and the boundary of  $I^3$  is a union of several univalent vertices of the graph. We call a univalent vertex on the boundary an *endpoint* of the tangle and call a vertex in the interior an *inner vertex* of the tangle. A  $d_1, \ldots, d_k$ -valent *tangle* is a tangle, each inner vertex of which has valency  $d_1, \ldots, d_{n-1}$ , or  $d_n$ . An (m, n)-tangle is a tangle with m top endpoints and n bottom endpoints.

Let f be a map from a set of tangle diagrams to a commutative ring R. For given scalars  $a_1, \ldots, a_n \in R$  and  $(n_t, n_b)$ -tangle diagrams  $T_1, \ldots, T_n$ , the local relation

$$a_1f(T_1) + \dots + a_nf(T_n) = 0$$

means that the equality

$$a_1f(L(T_1)) + \dots + a_nf(L(T_n)) = 0$$

holds for any tangle diagrams  $L(T_1), \ldots, L(T_n)$  which are identical outside a disk where they are the tangle diagrams  $T_1, \ldots, T_n$ . When f is an invariant of classical tangles, we call a local relation a *skein relation*.

The Alexander–Conway polynomial  $\Delta_L(t)$  of an oriented link L is characterized by the following:

• For the trivial knot  $\bigcirc$ , we have  $\Delta_{\bigcirc}(t) = 1$ .

• The skein relation

$$\Delta (t) - \Delta (t) = (t^{1/2} - t^{-1/2}) \Delta (t)$$

holds.

The bracket  $\langle D \rangle$  introduced in Definition 1.1 is also defined as a state sum, which ensures that the bracket is well-defined. We denote by C(D) the set of crossings of D. We denote by  $\operatorname{sgn}(c)$  the sign of a crossing c. A state  $\sigma$  of an oriented uni-trivalent (n, n)-tangle diagram D is an assignment of an element of  $\{0, 1, -1\}$  to each crossings:



which is a map from C(D) to  $\{0, 1, -1\}$ . We denote by S(D) the set of states of D. For a state  $\sigma$ , we define the *weight* wt $(c; \sigma)$  of a crossing c by

$$\operatorname{wt}(c;\sigma) = \begin{cases} 1 & \text{if } \sigma(c) = \operatorname{sgn}(c), \\ t^{-\operatorname{sgn}(c)} & \text{if } \sigma(c) = -\operatorname{sgn}(c), \\ -t^{-\operatorname{sgn}(c)} & \text{if } \sigma(c) = 0. \end{cases}$$

We denote by  $D_{\sigma}$  the digram obtained from D by replacing each crossing with

) 
$$\left(, \right)$$
, or  $\left(, \right)$ 

according to  $\sigma$ . We then have

$$\langle D \rangle = \sum_{\sigma \in S(D)} \prod_{c \in C(D)} \operatorname{wt}(c; \sigma) \delta(D_{\sigma}), \tag{1}$$

where

$$\delta(D_{\sigma}) = \begin{cases} 1 & \text{if } D_{\sigma} \text{ is a diagram of an acyclic tangle,} \\ 0 & \text{if } D_{\sigma} \text{ is a diagram of a cyclic tangle.} \end{cases}$$

From the state sum formula (1), we have the following lemma.

Lemma 2.1. We have

$$\left\langle \begin{array}{c} \left| \begin{array}{c} \\ \end{array}\right\rangle = \left\langle \\ \end{array}\right\rangle = \left\langle \begin{array}{c} \\ \end{array}\right\rangle, \quad \left\langle \begin{array}{c} \\ \end{array}\right\rangle = \left\langle \\ \end{array}\right\rangle, \quad \left\langle \begin{array}{c} \\ \end{array}\right\rangle = \left\langle \\ \end{array}\right\rangle, \quad \left\langle \begin{array}{c} \\ \end{array}\right\rangle = \left\langle \\ \end{array}\right\rangle, \quad \left\langle \begin{array}{c} \\ \end{array}\right\rangle, \quad \left\langle \begin{array}{c} \\ \end{array}\right\rangle = \left\langle \\ \end{array}\right\rangle, \quad \left\langle \begin{array}{c} \\ \end{array}\right\rangle, \quad \left\langle \begin{array}{c} \\ \end{array}\right\rangle = \left\langle \\ \end{array}\right\rangle, \quad \left\langle \begin{array}{c} \\ \end{array}\right\rangle, \quad \left\langle \begin{array}{c} \\ \end{array}\right\rangle, \quad \left\langle \end{array}\right\rangle, \quad \left\langle \end{array}\right\rangle, \quad \left\langle \begin{array}{c} \\ \end{array}\right\rangle, \quad \left\langle \end{array}\right\rangle, \quad \left\langle \end{array}\right\rangle, \quad \left\langle \begin{array}{c} \\ \end{array}\right\rangle, \quad \left\langle \right\rangle, \quad \left\langle \right$$



Figure 2: Top endpoints are connected

*Proof.* It is easy to see the equalities for diagrams without crossings. From the state sum formula (1), we have the equalities for any oriented uni-trivalent (n, n)-tangle diagrams.

Lemma 2.2. We have

$$\left\langle \begin{array}{c} \\ \end{array}\right\rangle \quad \left\langle \begin{array}{c} \\ \end{array}\right\rangle + \left\langle \begin{array}{c} \\ \end{array}\right\rangle = \left\langle \begin{array}{c} \\ \end{array}\right\rangle + \left\langle \begin{array}{c} \\ \end{array}\right\rangle \right\rangle.$$

*Proof.* It is sufficient to show the equality for diagrams without crossings. If the two top endpoints of the tangles are connected by a path outside the tangles as shown in Figure 2, we have

$$\left\langle \underbrace{\phantom{a}}_{} \right\rangle = 0 = \left\langle \underbrace{\phantom{a}}_{} \right\rangle, \qquad \left\langle \right\rangle = \left\langle \underbrace{\phantom{a}}_{} \right\rangle,$$

which imply the desired equality. In a similar manner, we have the desired equality in the following cases:

- (a) The two bottom endpoints of the tangles are connected by a path outside the tangles.
- (b) The two left endpoints of the tangles are connected by a path outside the tangles.
- (c) The two right endpoints of the tangles are connected by a path outside the tangles.

If no two of the endpoints of the tangles are connected by a path outside the tangles, we have

$$\left\langle \begin{array}{c} \\ \end{array}\right\rangle \quad \left\langle \begin{array}{c} \\ \end{array}\right\rangle = \left\langle \begin{array}{c} \\ \end{array}\right\rangle = \left\langle \begin{array}{c} \\ \end{array}\right\rangle = \left\langle \begin{array}{c} \\ \end{array}\right\rangle ,$$

which imply the desired equality.

Lemma 2.3. We have

$$\left\langle \begin{array}{c} \end{array}\right\rangle = \left\langle \begin{array}{c} \end{array}\right\rangle, \quad \left\langle \begin{array}{c} \end{array}\right\rangle = t^{-1} \left\langle \begin{array}{c} \end{array}\right\rangle + (1 - t^{-1}) \left\langle \begin{array}{c} \\ \end{array}\right\rangle, \\ \left\langle \end{array}\right\rangle, \quad \left\langle \begin{array}{c} \end{array}\right\rangle = t \left\langle \begin{array}{c} \end{array}\right\rangle + (1 - t) \left\langle \begin{array}{c} \end{array}\right\rangle + (1 - t) \left\langle \begin{array}{c} \end{array}\right\rangle.$$

*Proof.* By Lemma 2.1, we have

$$\left\langle \right\rangle = -t^{-1} \left\langle \right\rangle \left\langle \right\rangle + \left\langle \right\rangle + \left\langle \right\rangle + t^{-1} \left\langle \right\rangle \right\rangle = \left\langle \right\rangle.$$

In a similar manner, we have the other equalities.

Lemma 2.4. We have

*Proof.* By Lemma 2.1, we have

In a similar manner, we have the other equalities.

Lemma 2.5. We have



*Proof.* By Lemmas 2.1 and 2.4, we have



Proposition 2.6. We have



*Proof.* From the defining relations of  $\langle D \rangle$ , we have

$$\left\langle \left\langle \right\rangle \right\rangle = -t^{-1} \left\langle \left| \right\rangle \right\rangle + \left\langle \left\langle \right\rangle \right\rangle + t^{-1} \left\langle \left| \right\rangle \right\rangle = t^{-1} \left\langle \left| \right\rangle \right\rangle,$$

where the last equality follows from Lemma 2.1. In a similar manner, we

have

$$\left\langle \left| \right\rangle \right\rangle = \left\langle \left| \right\rangle \right\rangle, \quad \left\langle \left| \right\rangle \right\rangle = t \left\langle \left| \right\rangle \right\rangle, \quad \left\langle \left| \right\rangle \right\rangle = \left\langle \left| \right\rangle \right\rangle.$$

By Lemmas 2.2–2.4, we have



By Lemmas 2.3 and 2.5, we have



Proposition 2.7. We have

 $t^{1/2}\left\langle \right\rangle - t^{-1/2}\left\langle \right\rangle = (t^{1/2} - t^{-1/2})\left\langle \right\rangle \left\langle \right\rangle.$ 

*Proof.* The local relation follows from

$$t^{1/2}\left\langle \right\rangle = -t^{-1/2}\left\langle \right\rangle \left\langle \right\rangle + t^{1/2}\left\langle \right\rangle + t^{-1/2}\left\langle \right\rangle,$$
$$t^{-1/2}\left\langle \right\rangle = -t^{1/2}\left\langle \right\rangle \left\langle \right\rangle + t^{1/2}\left\langle \right\rangle + t^{-1/2}\left\langle \right\rangle.$$

Proposition 2.8. We have

$$t^{1/2} \left\langle \begin{array}{c} \downarrow \\ T \end{array} \right\rangle = t^{-1/2} \left\langle \begin{array}{c} \downarrow \\ T \end{array} \right\rangle$$

for any oriented classical (2, 2)-tangle T.

*Proof.* By Propositions 2.6 and 2.7, we have

$$\left\langle \begin{bmatrix} \mathbf{T} \\ \mathbf{T} \\ \mathbf{\dagger} & \mathbf{\dagger} \end{bmatrix} \right\rangle = \alpha \left\langle \mathbf{I} \right\rangle + \beta \left\langle \mathbf{I} \right\rangle \quad \left( \right\rangle$$

for some  $\alpha, \beta \in \mathbb{Z}[t^{\pm 1/2}]$ . We then have

$$\left\langle \begin{array}{c} 1\\ T\\ 1\end{array}\right\rangle = \alpha \left\langle \begin{array}{c} 1\\ 1\end{array}\right\rangle = t^{-1}\alpha \left\langle \begin{array}{c} 1\\ 1\end{array}\right\rangle = t^{-1}\alpha,$$
$$\left\langle \begin{array}{c} 1\\ T\\ 1\end{array}\right\rangle = \alpha \left\langle \begin{array}{c} 1\\ 1\end{array}\right\rangle = \alpha \left\langle \begin{array}{c} 1\\ 1\end{array}\right\rangle = \alpha,$$

which imply the desired equality.

*Proof of Theorem 1.2.* Let T be an oriented classical (n, n)-tangle. Let D be a diagram of T. By Proposition 2.6,

$$t^{\frac{\operatorname{rot}(D) + \operatorname{wr}(D)}{2}} \langle D \rangle$$

is invariant under the Reidemeister moves.

Let L be an oriented link, and let T be an oriented classical (1, 1)-tangle whose closure is L. Let D be a diagram of T. We define

$$X(L) := t^{\frac{\operatorname{rot}(D) + \operatorname{wr}(D)}{2}} \langle D \rangle.$$

By Proposition 2.8, X(L) does not depend on the choice of the oriented classical (1, 1)-tangle T whose closure is L. By Proposition 2.7, X(L) satisfies the skein relation

$$X\left(\swarrow\right) - X\left(\swarrow\right) = (t^{1/2} - t^{-1/2})X\left(\downarrow\right) \left(\downarrow\right).$$

We then have

$$\Delta_L(t) = X(L)$$

since both satisfy the same skein relation and  $\Delta_{\bigcirc}(t) = 1 = X(\bigcirc)$ . Therefore we have

$$\Delta_{\widehat{T}}(t) = X(\widehat{T}) = t^{\frac{\operatorname{rot}(D) + \operatorname{wr}(D)}{2}} \langle D \rangle.$$

## **3** Quandles and Alexander pairs

In this section, we will briefly recall quandles and Alexander pairs. For details, we refer the reader to [4, 5, 6]. Throughout this paper, for a positive integer n, we denote the cyclic group  $\mathbb{Z}/n\mathbb{Z}$  of order n as  $\mathbb{Z}_n$ .

A quandle [10, 13] is a non-empty set Q equipped with a binary operation  $\triangleleft : Q \times Q \rightarrow Q$  satisfying the following axioms:

- For any  $a \in Q$ ,  $a \triangleleft a = a$ .
- For any  $a \in Q$ , the map  $\triangleleft a : Q \to Q$  defined by  $\triangleleft a(x) = x \triangleleft a$  is bijective.
- For any  $a, b, c \in Q$ ,  $(a \triangleleft b) \triangleleft c = (a \triangleleft c) \triangleleft (b \triangleleft c)$ .

We denote by  $(\triangleleft a)^n : Q \to Q$  by  $\triangleleft^n a$  for  $n \in \mathbb{Z}$ . Then  $R_n = (\mathbb{Z}_n, \triangleleft)$  is a quandle, where  $a \triangleleft b = 2b - a$ . A trivial quandle is a quandle Q with a binary operation  $\triangleleft$  satisfying  $a \triangleleft b = a$  for any  $a, b \in Q$ . Let  $(Q_1, \triangleleft_1)$  and  $(Q_2, \triangleleft_2)$  be quandles. A quandle homomorphism from  $Q_1$  to  $Q_2$  is defined to be a map  $f : Q_1 \to Q_2$  satisfying  $f(a \triangleleft_1 b) = f(a) \triangleleft_2 f(b)$  for any  $a, b \in Q_1$ . A quandle representation  $\rho$  of a quandle X into a quandle Q is a quandle homomorphism  $\rho : X \to Q$ .



Figure 3:

Let Q be a quandle. Let D be a diagram of an oriented classical (n, n)tangle T. A Q-coloring of D is a map  $C : \mathcal{A}(D) \to Q$  satisfying the condition

$$C(u_c) \triangleleft C(v_c) = C(w_c)$$

for each crossing  $c \in C(D)$ , where  $u_c$ ,  $v_c$  and  $w_c$  are the arcs forming the crossing c as shown in the left picture of Figure 3. Here, the normal orientation is obtained by rotating the usual orientation counterclockwise by  $\pi/2$  on the diagram. A Q-coloring is trivial if it is a constant map. A colored classical (n, n)-tangle is an oriented classical (n, n)-tangle T with a  $\mathbb{Z}_{>0}$ -coloring  $\rho$ , where  $\mathbb{Z}_{>0}$  is a trivial quandle. We denote by  $\operatorname{Col}_Q(D)$  the set of Q-colorings of D. Let D' be a diagram of T obtained by applying a single Reidemeister move to D. Then, each Q-coloring C of D has a unique Q-coloring C' of D'that coincides with C except in the disk in which the move is applied. This gives a one-to-one correspondence between  $\operatorname{Col}_Q(D)$  and  $\operatorname{Col}_Q(D')$ . The colored Reidemeister moves are listed in Figure 4, which are the Reidemeister moves with corresponding Q-colorings.

For a quandle  $(Q, \triangleleft)$ , a *Q*-set is a non-empty set *Y* equipped with a map  $\triangleleft : Y \times Q \rightarrow Y$  satisfying the following axioms:

- For any  $a \in Q$ , the map  $\triangleleft a : Y \to Y$  defined by  $\triangleleft a(y) = y \triangleleft a$  is bijective.
- For any  $y \in Y$  and  $a, b \in Q$ , we have  $(y \triangleleft a) \triangleleft b = (y \triangleleft b) \triangleleft (a \triangleleft b)$ .

The associated group  $\operatorname{As} Q$  of a quandle Q is a group defined by the presentation:

$$\langle x \ (x \in Q) \ | \ x \triangleleft y = y^{-1} x y \ (x, y \in Q) \rangle.$$

Then As Q is a Q-set with  $y \triangleleft a = ya$ . Let  $(Y_1, \triangleleft_1)$  and  $(Y_2, \triangleleft_2)$  be Q-sets. A Q-set homomorphism from  $Y_1$  to  $Y_2$  is defined to be a map  $f : Y_1 \rightarrow Y_2$ satisfying  $f(y \triangleleft_1 a) = f(y) \triangleleft_2 a$  for any  $y \in Y_1$  and  $a \in Q$ . Let D be a diagram of an oriented link L. We denote by  $\mathcal{SA}(D)$  the set of semi-arcs of D, where a semi-arc is a piece of a curve such that the endpoints of the piece are crossings. We denote by  $\mathcal{R}(D)$  the set of complementary regions of D. For a semi-arc  $\alpha$ , we denote by  $r(\alpha)$  and  $r'(\alpha)$  the regions facing the



Figure 4: Colored Reidemeister moves

semi-arc  $\alpha$  as shown in the right picture of Figure 3. For an arc  $\alpha$ , we set  $r(\alpha) := r(\alpha_0)$  and  $r'(\alpha) := r'(\alpha_0)$ , where  $\alpha_0$  is the semi-arc that originates from the arc  $\alpha$  and shares its initial point with the arc  $\alpha$ . Let Y be a Q-set. A  $Q_Y$ -coloring  $\rho_Y$  of D is an extension of a Q-coloring  $\rho$  of D that assigns an element of Y to each region of D satisfying the condition

$$\rho_Y(r(\alpha)) \triangleleft \rho(\alpha) = \rho_Y(r'(\alpha))$$

for each semi-arc  $\alpha \in \mathcal{A}(D)$ , where the color  $\rho(\alpha)$  of a semi-arc  $\alpha$  is defined by the color of the arc from which the semi-arc originates. We denote by  $\tilde{\rho}$ the  $Q_{\text{As}Q}$ -coloring that is the extension of  $\rho$  satisfying  $\tilde{\rho}(r_{\text{out}}) = 1$ , where  $r_{\text{out}}$ is the outermost region of D.

Let Q be a quandle, and let R be a unital ring. The pair  $(f_1, f_2)$  of maps  $f_1, f_2: Q \times Q \to R$  is an Alexander pair [6] if  $f_1$  and  $f_2$  satisfy the following conditions:

- For any  $a \in Q$ ,  $f_1(a, a) + f_2(a, a) = 1$ .
- For any  $a, b \in Q$ ,  $f_1(a, b)$  is invertible.
- For any  $a, b, c \in Q$ ,

$$f_1(a \triangleleft b, c)f_1(a, b) = f_1(a \triangleleft c, b \triangleleft c)f_1(a, c),$$
  

$$f_1(a \triangleleft b, c)f_2(a, b) = f_2(a \triangleleft c, b \triangleleft c)f_1(b, c), \text{ and}$$
  

$$f_2(a \triangleleft b, c) = f_1(a \triangleleft c, b \triangleleft c)f_2(a, c) + f_2(a \triangleleft c, b \triangleleft c)f_2(b, c)$$

Assuming that  $f_1(a, b) + f_2(a, b) = 1$  for any  $a, b \in Q$ , we have the last equality follows from the other conditions, since we have

$$\begin{aligned} f_1(a \triangleleft c, b \triangleleft c) f_2(a, c) + f_2(a \triangleleft c, b \triangleleft c) f_2(b, c) &- f_2(a \triangleleft b, c) \\ &= -f_1(a \triangleleft c, b \triangleleft c) f_1(a, c) - f_2(a \triangleleft c, b \triangleleft c) f_1(b, c) + f_1(a \triangleleft b, c) \\ &= -f_1(a \triangleleft b, c) f_1(a, b) - f_1(a \triangleleft b, c) f_2(a, b) + f_1(a \triangleleft b, c) = 0. \end{aligned}$$

Let  $(f_1, f_2)$  be an Alexander pair. A column relation map  $f_{col} : Q \to R$  is a map satisfying

$$f_{\rm col}(a \triangleleft b) = f_1(a, b) f_{\rm col}(a) + f_2(a, b) f_{\rm col}(b)$$

for any  $a, b \in Q$ . For each  $c \in Q$ , the map  $f_{col} : Q \to R$  defined by  $f_{col}(a) = f_2(a \triangleleft^{-1} c, c)$  is a column relation map ([5]).

Let  $(f_1, f_2)$  be an Alexander pair. Let Y be a Q-set. A row relation map  $f_{row}: Y \times Q \to R$  is a map satisfying

$$f_{\text{row}}(y,a) = f_{\text{row}}(y \triangleleft b, a \triangleleft b) f_1(a,b), \text{ and}$$
  
$$f_{\text{row}}(y \triangleleft a, b) = f_{\text{row}}(y,b) + f_{\text{row}}(y \triangleleft b, a \triangleleft b) f_2(a,b)$$

for any  $a, b \in Q$  and  $y \in Y$ . Let Y be the Q-set  $Q \times R^{\times}$  with  $(y, z) \triangleleft a := (y \triangleleft a, f_1(y, a)z)$ . The map  $f_{\text{row}} : Y \times Q \to R$  defined by  $f_{\text{row}}((y, z), a) = z^{-1}f_1(y, a)^{-1}f_2(y, a)$  is a row relation map ([4]). For each  $c \in Q$ , the map  $f_{\text{row}}$ : As  $Q \times Q \to R$  defined by  $f_{\text{row}}(y, a) = f_{\text{row}}(\varphi_c(y), a)$  is a row relation map, where  $\varphi_c$ : As  $Q \to Y$  is the Q-set homomorphism satisfying  $\varphi_c(1) = (c, 1)$ .

# 4 A bracket polynomial for an $(f_1, f_2)$ -twisted Alexander invariant with $f_1 + f_2 = 1$

**Definition 4.1.** Let Q be a quandle, and let R be a commutative ring. Let  $(f_1, f_2)$  be an Alexander pair of  $f_1, f_2 : Q \times Q \to R$  satisfying  $f_1(a, b) + f_2(a, b) = 1$  for any  $a, b \in Q$ . Let D be a diagram of an oriented 1, 2, 3-valent (n, n)-tangle T, and let  $\rho : \mathcal{A}(D) \to Q$  be a map. We define  $\langle (D, \rho) \rangle \in R$  by the local relations

and, for a diagram D without crossings,

$$\langle (D, \rho) \rangle = \begin{cases} 1 & \text{if } D \text{ is a diagram of an acyclic tangle,} \\ 0 & \text{if } D \text{ is a diagram of a cyclic tangle.} \end{cases}$$

Let D be a diagram of an oriented classical (n, n)-tangle T, and let  $K_1, \ldots, K_r$  be the connected components of T. Let  $D(K_i)$  be the diagram of  $K_i$  that is obtained by removing the other connected components from D. We then have  $\operatorname{rot}(D) = \sum_{i=1}^r \operatorname{rot}(D(K_i))$ .

**Proposition 4.2.** Let T be an oriented classical (n, n)-tangle, and let D be a diagram of T. Let  $\rho : \mathcal{A}(D) \to Q$  be a quandle coloring. We fix  $\omega_1, \ldots, \omega_r \in \mathbb{R}^{\times}$  so that  $\omega_i = f_1(\rho(\alpha), \rho(\alpha))$  for some  $\alpha \in \mathcal{A}(D; K_i)$ . Then

$$\left(\prod_{i=1}^{r} \omega_{i}^{\frac{\operatorname{rot}(D(K_{i})) + \operatorname{wr}(D(K_{i})) + 1}{2}}\right)^{-1} \langle (D, \rho) \rangle$$

is invariant under the colored Reidemeister moves.

We remark that  $f_1(\rho(\alpha), \rho(\alpha))$  does not depend on the choice of the arc  $\alpha$ , since  $f_1(\rho(\alpha), \rho(\alpha)) = f_1(\rho(\alpha) \triangleleft c, \rho(\alpha) \triangleleft c)$  follows from  $f_1(a \triangleleft a, c)f_1(a, a) = f_1(a \triangleleft c, a \triangleleft c)f_1(a, c)$ .

The bracket  $\langle (D, \rho) \rangle$  introduced in Definition 4.1 is also defined as a state sum, which ensures that the bracket is well-defined. A *state*  $\sigma$  of D is an assignment of an element of  $\{0, 1, -1\}$  to each crossings:



which is a map from C(D) to  $\{0, 1, -1\}$ . For a state  $\sigma$ , we define the *weight* wt $(c; \sigma)$  of a crossing c by

$$\operatorname{wt}(c;\sigma) = \begin{cases} 1 & \text{if } \sigma(c) = \operatorname{sgn}(c), \\ f_1(\rho(u_c), \rho(v_c))^{\operatorname{sgn}(c)} & \text{if } \sigma(c) = -\operatorname{sgn}(c), \\ -f_1(\rho(u_c), \rho(v_c))^{\operatorname{sgn}(c)} & \text{if } \sigma(c) = 0. \end{cases}$$

We denote by  $D_{\sigma}$  the digram obtained from D by replacing each crossing with

$$\begin{array}{c} \begin{array}{c} \\ \end{array} \end{array} , \begin{array}{c} \\ \end{array} , \begin{array}{c} \\ \end{array} , \begin{array}{c} \\ \end{array} , \begin{array}{c} \\ \end{array} or \end{array}$$

according to  $\sigma$ . We then have

$$\langle (D, \rho) \rangle = \sum_{\sigma \in S(D)} \prod_{c \in C(D)} \operatorname{wt}(c; \sigma) \delta(D_{\sigma}),$$

where

 $\delta(D_{\sigma}) = \begin{cases} 1 & \text{if } D_{\sigma} \text{ is a diagram of an acyclic tangle,} \\ 0 & \text{if } D_{\sigma} \text{ is a diagram of a cyclic tangle.} \end{cases}$ 

In a similar way as in Section 2, we have the following lemmas and proposition.

Lemma 4.3. We have

for  $a \in Q$ ,  $m \in \{0, 1, 2\}$  and  $n \ge 0$ , where we omit colors of the arcs. There are no restrictions between the omitted colors other than the requirement that the colors of the corresponding endpoints are the same.

Lemma 4.4. We have

$$\begin{pmatrix} a \\ b \end{pmatrix} \begin{pmatrix} c \\ d \end{pmatrix} + \begin{pmatrix} a & c \\ b & d \end{pmatrix} = \begin{pmatrix} a & c \\ b & d \end{pmatrix} + \begin{pmatrix} a & c \\ b & d \end{pmatrix}$$

for  $a, b, c, d \in Q$ .

Lemma 4.5. We have

$$\begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} a \\ b \end{pmatrix}, \quad \begin{pmatrix} a \\ a \end{pmatrix} = \begin{pmatrix} a \\ b \end{pmatrix}, \quad \begin{pmatrix} a \\ a \end{pmatrix} = \begin{pmatrix} a \\ b \end{pmatrix}, \\ \begin{pmatrix} a \\ a \end{pmatrix} = f_1(a, b) \begin{pmatrix} a \\ a \end{pmatrix} + (1 - f_1(a, b)) \begin{pmatrix} a \\ a \end{pmatrix}, \\ \begin{pmatrix} b \\ a \end{pmatrix} = f_1(a, b)^{-1} \begin{pmatrix} b \\ a \end{pmatrix} + (1 - f_1(a, b)^{-1}) \begin{pmatrix} b \\ a \end{pmatrix} + (1 - f_1(a, b)^{-1$$

for  $a, b \in Q$ .

Lemma 4.6. We have

$$\left\langle b \triangleleft^{-1} a \bigvee_{a \downarrow}^{+C} \right\rangle = \left\langle \begin{array}{c} \downarrow c \\ a \downarrow b \\ a \downarrow b \\ \end{array} \right\rangle = \left\langle \begin{array}{c} \downarrow c \\ a \triangleleft b \\ a \downarrow b \\ \end{array} \right\rangle,$$

$$f_1(a \triangleleft^{-1} b, b) \left\langle \begin{array}{c} a \bigvee_{b \downarrow}^{+C} \\ \downarrow a \downarrow b \\ a \triangleleft^{-1} b \\ \downarrow c \\ \end{array} \right\rangle = \left\langle \begin{array}{c} a \downarrow b \\ \downarrow c \\ \downarrow c \\ \end{array} \right\rangle = \left\langle \begin{array}{c} a \downarrow b \\ \downarrow c \\ \downarrow c \\ \end{array} \right\rangle,$$

$$\left\langle \begin{array}{c} a \downarrow b \\ \downarrow c \\ \downarrow c \\ \end{array} \right\rangle = \left\langle \begin{array}{c} a \downarrow b \\ \downarrow c \\ \downarrow c \\ \end{array} \right\rangle = \left\langle \begin{array}{c} a \downarrow b \\ \downarrow c \\ \downarrow c \\ \end{array} \right\rangle,$$

$$\left\langle \begin{array}{c} a \downarrow b \\ \downarrow c \\ \downarrow c \\ \end{matrix} \right\rangle = f_1(b, a)^{-1} \left\langle \begin{array}{c} a \downarrow b \\ b \triangleleft a \downarrow c \\ \downarrow c \\ \end{matrix} \right\rangle,$$

for  $a, b, c \in Q$ .

### Lemma 4.7. We have



for  $b, c, d \in Q$ .

**Proposition 4.8.** We have

for  $a, b, c \in Q$ .

Proposition 4.2 follows from this proposition.

**Proposition 4.9.** Let T be an oriented classical (n, n)-tangle containing a split link component L, which is a link component of T with a 2-sphere separating L from T - L. Let D be a diagram of T. Let  $\rho : \mathcal{A}(D) \to Q$  be a quandle coloring. Then, we have  $\langle (D, \rho) \rangle = 0$ .

*Proof.* By Proposition 4.8, we may assume that  $D = D_{T-L} \sqcup D_L$ , that is, there is a circle separating L from T-L on the diagram D, where  $D_{T-L}$  and  $D_L$  are diagrams of T-L and L, respectively. Since any state of  $D_L$  has a cycle, we have  $\langle (D, \rho) \rangle = 0$ .

## 5 A bracket polynomial for the multivariable Alexander polynomial

Let  $Q := \mathbb{Z}_{>0}$  be the trivial quandle, and let  $R := \mathbb{Z}[t_1^{\pm 1}, t_2^{\pm 1}, \ldots]$ . Let  $(f_1, f_2)$  be an Alexander pair of maps  $f_1, f_2 : Q \times Q \to R$  defined by  $f_1(a, b) = t_b^{-1}$  and

 $f_2(a,b) = 1 - t_b^{-1}$ . Then, the bracket polynomial introduced in Definition 4.1 coincides with the bracket polynomial introduced in Definition 1.3. In this section, we discuss this bracket polynomial  $\langle (D,\rho) \rangle$ .

#### Lemma 5.1. We have



for  $a, b \in \mathbb{Z}_{>0}$ .

*Proof.* By Lemmas 4.3 and 4.6, we have



In a similar manner, we have the other local relation.

Proposition 5.2. We have

$$t_a^{1/2} \left\langle \begin{array}{c} a \\ a \end{array} \right\rangle - t_a^{-1/2} \left\langle \begin{array}{c} a \\ a \end{array} \right\rangle = (t_a^{1/2} - t_a^{-1/2}) \left\langle \begin{array}{c} a \\ a \end{array} \right\rangle, \qquad (2)$$

$$t_a \left\langle \bigcup_{i=1}^{n} \right\rangle + t_b^{-1} \left\langle \bigcup_{i=1}^{n} \right\rangle = (t_a + t_b^{-1}) \left\langle \bigcup_{i=1}^{n} \right\rangle, \tag{3}$$

$$\begin{array}{c} a & b & c \\ \alpha_{1} \left\langle \begin{array}{c} & \\ \end{array} \right\rangle \right\rangle + \alpha_{2} \left\langle \begin{array}{c} & \\ \end{array} \right\rangle + \alpha_{3} \left\langle \begin{array}{c} & \\ \end{array} \right\rangle \right\rangle + \alpha_{3} \left\langle \begin{array}{c} & \\ \end{array} \right\rangle \right\rangle + \alpha_{3} \left\langle \begin{array}{c} & \\ \end{array} \right\rangle \right\rangle + \alpha_{3} \left\langle \begin{array}{c} & \\ \end{array} \right\rangle \right\rangle + \alpha_{3} \left\langle \begin{array}{c} & \\ \end{array} \right\rangle \right\rangle + \alpha_{3} \left\langle \begin{array}{c} & \\ \end{array} \right\rangle \right\rangle + \alpha_{3} \left\langle \begin{array}{c} & \\ \end{array} \right\rangle \right\rangle + \alpha_{3} \left\langle \begin{array}{c} & \\ \end{array} \right\rangle \right\rangle + \alpha_{3} \left\langle \begin{array}{c} & \\ \end{array} \right\rangle \right\rangle + \alpha_{3} \left\langle \begin{array}{c} & \\ \end{array} \right\rangle \right\rangle + \alpha_{3} \left\langle \begin{array}{c} & \\ \end{array} \right\rangle \right\rangle + \alpha_{3} \left\langle \begin{array}{c} & \\ \end{array} \right\rangle \right\rangle + \alpha_{3} \left\langle \begin{array}{c} & \\ \end{array} \right\rangle \right\rangle + \alpha_{3} \left\langle \begin{array}{c} & \\ \end{array} \right\rangle \right\rangle + \alpha_{3} \left\langle \begin{array}{c} & \\ \end{array} \right\rangle \right\rangle = 0, \quad (4)$$

for  $a, b, c \in \mathbb{Z}_{>0}$ , where

$$\begin{aligned} \alpha_1 &= t_a t_b t_c - t_a t_c + t_b t_c - t_c, & \alpha_2 &= -t_a t_b t_c - t_a t_b + t_a t_c + t_a, \\ \alpha_3 &= t_a t_b - t_b t_c, & \alpha_4 &= -t_a + t_b - t_a t_c^{-1} + t_b t_c, \\ \alpha_5 &= -t_a t_b + t_a^{-1} t_c - t_b + t_c, & \alpha_6 &= t_a t_c^{-1} - t_a^{-1} t_c. \end{aligned}$$

*Proof.* Using Lemma 5.1, we have the equalities.

Proposition 5.3. We have



for any oriented classical (2, 2)-tangle T.



Figure 5: A collection of positive full-twists

*Proof.* By Propositions 4.8, 4.9 and 5.2, we have

$$\left\langle \begin{bmatrix} a & b \\ T \\ \downarrow & \downarrow \\ a & b \\ \end{array} \right\rangle = \alpha \left\langle \begin{bmatrix} a & b \\ \downarrow & \downarrow \\ \downarrow & \downarrow \\ \end{array} \right\rangle + \beta \left\langle \downarrow & \downarrow \\ \downarrow & \downarrow \\ \end{array} \right\rangle$$
(6)

for some  $\alpha, \beta \in \mathbb{Z}[t_1^{\pm 1/2}, t_2^{\pm 1/2}, \ldots]$ . See [15]. We then have

which imply the desired equality.

**Remark 5.4.** We give a concrete procedure to obtain (6). In the following procedure, we freely use Proposition 4.8. Let  $(T, \rho)$  be a colored oriented classical (2, 2)-tangle, and let D be a diagram of T.

- 1. We focus on a circle component K of T. By using (2), we can transform K into trivial links without self-crossings. Strictly speaking,  $\langle D \rangle$  is a linear combination of  $\langle D_1 \rangle, \ldots, \langle D_n \rangle$ , where  $D_i$  is an oriented classical (2, 2)-tangle whose circle component corresponding to K is a trivial link without self-crossings in  $D_i$ .
- 2. By using (3), we can transform the diagrams in Step 1 into diagrams in which the intersection of K and the other connected components is a collection of positive full-twists as shown in Figure 5, where thickened strands correspond to K.

3. By using (4), we can transform two positive full-twists into one or zero two positive full-twist:



where thickened strands correspond to K. Repeating this transformation, we can transform the diagrams in Step 2 into diagrams in which the intersection of each circle component of K and the other connected components is one or zero positive full-twist.

- 4. By using (5) and Proposition 4.9, we can remove K from T.
- 5. Repeating Steps 1–4, we may assume that T has no circle components. Applying the transformations in Steps 1–3 to the right strand of T, we obtain the diagrams



6. By using (2), we can transform the diagrams in Step 5 into the diagrams



7. By using (5), we can transform the diagrams in Step 6 into the diagrams



Proof of Theorem 1.4. Let  $(T, \rho)$  be a colored oriented classical (n, n)-tangle, and let D be a diagram of T. Let  $K_1, \ldots, K_r$  be the connected components

of T. By Proposition 4.2,

$$\prod_{i=1}^{r} t_{\rho(K_{i})}^{\frac{\operatorname{rot}(D(K_{i})) + \operatorname{wr}(D;K_{i})}{2}} \langle (D,\rho) \rangle = \prod_{i=1}^{r} t_{\rho(K_{i})}^{\frac{\operatorname{lk}(K_{i}, L-K_{i}) - 1}{2}} \prod_{i=1}^{r} t_{\rho(K_{i})}^{\frac{\operatorname{rot}(D(K_{i})) + \operatorname{wr}(D(K_{i})) + 1}{2}} \langle (D,\rho) \rangle$$

is invariant under the colored Reidemeister moves.

Let L be an oriented link, and let T be an oriented classical (1, 1)-tangle whose closure is L. Let D be a diagram of T. Let  $K_1, \ldots, K_r$  be the connected components of T such that  $T_j$  is a strand connecting the end points of T. We then define

$$X(L,\rho) := \frac{\prod_{i=1}^{r} t_i^{\frac{\operatorname{rot}(D(K_i)) + \operatorname{wr}(D;K_i)}{2}} \langle (D,\rho) \rangle}{t_j^{1/2} - t_j^{-1/2}}.$$

By Proposition 5.3,  $X(L,\rho)$  does not depend on the choice of the oriented classical (1, 1)-tangle T whose closure is L. By Proposition 5.2,  $X(L,\rho)$  satisfies the skein relation

$$\begin{split} X \begin{pmatrix} a & a \\ & \ddots \end{pmatrix} - X \begin{pmatrix} a & a \\ & \ddots \end{pmatrix} &= (t_a^{1/2} - t_a^{-1/2}) X \begin{pmatrix} a & a \\ & \ddots \end{pmatrix}, \\ X \begin{pmatrix} a & b \\ & \ddots \end{pmatrix} &+ X \begin{pmatrix} a & b \\ & \ddots \end{pmatrix} &= (t_a^{1/2} t_b^{1/2} + t_a^{-1/2} t_b^{-1/2}) X \begin{pmatrix} a & b \\ & & \ddots \end{pmatrix}, \\ \beta_1 X \begin{pmatrix} a & b & c \\ & \ddots & \ddots \end{pmatrix} &+ \beta_2 X \begin{pmatrix} a & b & c \\ & & \ddots & \ddots \end{pmatrix} &+ \beta_3 X \begin{pmatrix} a & b & c \\ & & \ddots & \ddots \end{pmatrix} &+ \beta_3 X \begin{pmatrix} a & b & c \\ & & \ddots & \ddots \end{pmatrix} \\ &+ \beta_4 X \begin{pmatrix} a & b & c \\ & & \ddots & \ddots \end{pmatrix} &+ \beta_5 X \begin{pmatrix} a & b & c \\ & & & \ddots & \ddots \end{pmatrix} &+ \beta_6 X \begin{pmatrix} a & b & c \\ & & & & \ddots \end{pmatrix} &= 0, \\ X \begin{pmatrix} a & b & c \\ & & & & \ddots \end{pmatrix} &= (t_a^{1/2} - t_a^{-1/2}) X \begin{pmatrix} a \\ & & & & & \ddots \end{pmatrix} \end{split}$$

for  $a, b, c \in \mathbb{Z}_{>0}$ , where

$$\begin{split} \beta_1 &= t_a^{1/2} t_b^{1/2} - t_a^{1/2} t_b^{-1/2} + t_a^{-1/2} t_b^{1/2} - t_a^{-1/2} t_b^{-1/2}, \\ \beta_2 &= -t_b^{1/2} t_c^{1/2} - t_b^{1/2} t_c^{-1/2} + t_b^{-1/2} t_c^{1/2} + t_b^{-1/2} t_c^{-1/2}, \\ \beta_3 &= t_a^{1/2} t_c^{-1/2} - t_a^{-1/2} t_c^{1/2}, \\ \beta_4 &= -t_a^{1/2} t_b^{-1/2} + t_a^{-1/2} t_b^{1/2} - t_a^{1/2} t_b^{-1/2} t_c^{-1} + t_a^{-1/2} t_b^{1/2} t_c, \\ \beta_5 &= -t_a t_b^{1/2} t_c^{-1/2} + t_a^{-1} t_b^{-1/2} t_c^{1/2} - t_b^{1/2} t_c^{-1/2} + t_b^{-1/2} t_c^{1/2}, \\ \beta_6 &= t_a t_c^{-1} - t_a^{-1} t_c. \end{split}$$

By the definition of  $X(L, \rho)$ , we have

$$X\left(\bigcirc\right) = \left\langle j \right\rangle = \frac{1}{t_j^{1/2} - t_j^{-1/2}}.$$

By Proposition 4.9, we have

$$X(L,\rho) = 0$$

for any split link L. Then, by [15, Theorem 7.2], we have

$$\Delta_L(t_1,\ldots,t_r)=X(L).$$

Therefore, we have

$$\Delta_{\widehat{T}}(t_1,\ldots,t_r) = X(\widehat{T}) = \frac{\prod_{i=1}^r t_i^{\frac{\operatorname{rot}(D(K_i)) + \operatorname{wr}(D;K_i)}{2}} \langle (D,\rho) \rangle}{t_j^{1/2} - t_j^{-1/2}}.$$

## 6 The quandle twisted Alexander invariant

In this section, we recall an equivalence relation on triples of matrices and their row and column relation matrices, and see how to obtain the triples from an oriented link and its quandle representation. For details, we refer the reader to [7].

Let R be a unital ring. We denote by  $R^{\times}$  the group of units of R. We denote by M(m, n; R) the set of  $m \times n$  matrices over R and denote by GL(n; R) the set of  $n \times n$  invertible matrices over R. For  $A = (a_{ij}) \in$   $M(m, n; R), \, i = (i_1, \dots, i_s) \text{ and } j = (j_1, \dots, j_t), \text{ we define}$ 

$$A_{i,j} := \begin{pmatrix} a_{i_1j_1} & a_{i_1j_2} & \cdots & a_{i_1j_t} \\ a_{i_2j_1} & a_{i_2j_2} & \cdots & a_{i_2j_t} \\ \vdots & \vdots & \ddots & \vdots \\ a_{i_sj_1} & a_{i_sj_2} & \cdots & a_{i_sj_t} \end{pmatrix}.$$

Let  $S_n$  be the symmetric group on  $\{1, \ldots, n\}$ . We denote by  $\operatorname{sgn} \sigma$  the sign of  $\sigma \in S_n$ . Put  $\overline{n} := (1, \ldots, n)$ . For  $\sigma \in S_n$ , we set

$$\sigma(i_1,\ldots,i_s) := (\sigma(i_1),\ldots,\sigma(i_s)),$$
  
$$(i_1,\ldots,i_s) + k := (i_1+k,\ldots,i_s+k).$$

Let  $A \in M(d + m, d + n; R)$ , where d, m, n > 0. We call  $B \in M(m, d + m; R)$  a row relation matrix of A if BA = O. A row relation matrix  $B \in M(m, d + m; R)$  is regular if  $B_{\overline{m},\sigma(\overline{m})}$  is invertible for some  $\sigma \in S_{d+m}$ . We call  $C \in M(d + n, n; R)$  a column relation matrix of A if AC = O. A column relation matrix  $C \in M(d + n, n; R)$  is regular if  $C_{\tau(\overline{n}),\overline{n}}$  is invertible for some  $\tau \in S_{d+n}$ . We define  $P_{ij}, E_{ij}(r), E_i(u) \in GL(n; R)$  by

$$P_{ij} = (e_1, \dots, e_{i-1}, e_j, e_{i+1}, \dots, e_{j-1}, e_i, e_{j+1}, \dots, e_n),$$
  

$$E_{ij}(r) = (e_1, \dots, e_{j-1}, e_j + re_i, e_{j+1}, \dots, e_n) \quad (i \neq j),$$
  

$$E_i(u) = (e_1, \dots, e_{i-1}, ue_i, e_{i+1}, \dots, e_n)$$

for  $r \in R$  and  $u \in R^{\times}$ , where  $e_i$  is the unit column vector whose components are all 0, except the *i*th component that equals 1. We write  $(B, A, C) \sim (B', A', C')$  if they are related by a finite sequence of the following transformations:

•  $(B, A, C) \leftrightarrow (BE_{ij}(r)^{-1}, E_{ij}(r)A, C) \ (r \in R),$ 

• 
$$(B, A, C) \leftrightarrow (B, AE_{ij}(r), E_{ij}(r)^{-1}C) \ (r \in R),$$

• 
$$(B, A, C) \leftrightarrow (BE_i(u), E_i(u)^{-1}AE_j(u), E_j(u)^{-1}C) \ (u \in \mathbb{R}^{\times}),$$

• 
$$(B, A, C) \leftrightarrow \left( \begin{pmatrix} B & \mathbf{0} \end{pmatrix}, \begin{pmatrix} A & \mathbf{0} \\ \mathbf{0} & 1 \end{pmatrix}, \begin{pmatrix} C \\ \mathbf{0} \end{pmatrix} \right)$$

Let R be a field. Let  $A \in M(d+m, d+n; R)$ . Let  $B \in M(m, d+m; R)$  be a regular row relation matrix of A, and let  $C \in M(d+n, n; R)$  be a regular column relation matrix of A. We choose  $\sigma \in S_{d+m}$  and  $\tau \in S_{d+n}$  so that  $B_{\overline{m},\sigma(\overline{m})}$  and  $C_{\tau(\overline{n}),\overline{n}}$  are invertible. We then define

$$\Delta(B, A, C) := \frac{\operatorname{sgn} \sigma \operatorname{sgn} \tau \det A_{\sigma(\overline{d}+m), \tau(\overline{d}+n)}}{\det B_{\overline{m}, \sigma(\overline{m})} \det C_{\tau(\overline{n}), \overline{n}}},$$



#### Figure 6:

which is an invariant of the equivalence class of (B, A, C).

Let Q be a quandle and R a unital ring. Let  $(f_1, f_2)$  be an Alexander pair of maps  $f_1, f_2 : Q \times Q \to R$ . Let  $L = K_1 \cup \cdots \cup K_r$  be an oriented r-component link, and let  $\rho : Q(L) \to Q$  be a quandle representation. Let D be a diagram of L such that every component has an undercrossing. Let  $c_1, \ldots, c_n$  be the crossings of D. We denote by  $x_i$  the arc starting from a crossing  $c_i$  for each i (see the left picture of Figure 6). We denote by  $u_i, w_i$ and  $v_i$  the under-arcs and over-arc, respectively, of a crossing  $c_i$  such that the normal orientation of  $v_i$  points from  $u_i$  to  $w_i$  (see the right picture of Figure 6).

We define  $A(D, \rho; f_1, f_2)$  as the  $n \times n$  matrix whose (i, j)-entry  $a_{ij}$  is given by

$$a_{ij} = \delta(u_i, x_j) f_1(a_i, b_i) + \delta(v_i, x_j) f_2(a_i, b_i) - \delta(w_i, x_j) g_2(a_i, b_i) - \delta(w_i, b_i) - \delta(w_i$$

where  $a_i = \rho(u_i), b_i = \rho(v_i)$ , and

$$\delta(x,y) := \begin{cases} 1 & \text{if } x = y, \\ 0 & \text{otherwise.} \end{cases}$$

We denote by  $C_+(D)$  and  $C_-(D)$  the sets of positive and negative crossings of D, respectively. We denote by #S the number of elements of a set S. We fix  $\omega_1, \ldots, \omega_r \in \mathbb{R}^{\times}$  so that  $\omega_i = f_1(\rho(\alpha), \rho(\alpha))$  for some  $\alpha \in \mathcal{A}(D; K_i)$ . We define

$$\widetilde{A}(D,\rho;f_1,f_2) := \begin{pmatrix} A(D,\rho;f_1,f_2) & \mathbf{0} \\ \mathbf{0} & \operatorname{cor}(D,\rho;f_1,f_2)^{-1} \end{pmatrix},$$

where

$$\operatorname{cor}(D,\rho;f_1,f_2) = (-1)^{\#C_+(D)} \prod_{i=1}^r \omega_i^{\frac{\operatorname{rot}(D(K_i)) + \operatorname{wr}(D(K_i)) + 1}{2}} \prod_{c \in C_-(D)} f_1(\rho(u_c),\rho(v_c)).$$

For column relation maps  $f_{\text{col},1}, \ldots, f_{\text{col},m} : Q \to R$ , we define

$$R_{\rm col}(D,\rho;f_{{\rm col},1},\ldots,f_{{\rm col},m}) := \begin{pmatrix} f_{{\rm col},1}(\rho(x_1)) & \cdots & f_{{\rm col},m}(\rho(x_1)) \\ \vdots & \ddots & \vdots \\ f_{{\rm col},1}(\rho(x_n)) & \cdots & f_{{\rm col},m}(\rho(x_n)) \end{pmatrix}.$$



Figure 7:

We denote  $R_{col}(D, \rho; f_{col,1}, \ldots, f_{col,m})$  by  $R_{col}(D, \rho; f_{col})$  for short. We define

$$\widetilde{R_{\text{col}}}(D,\rho; \boldsymbol{f_{\text{col}}}) := \begin{pmatrix} R_{\text{col}}(D,\rho; \boldsymbol{f_{\text{col}}}) \\ \mathbf{0} \end{pmatrix}.$$

We define  $r_i := r(\alpha(w_i; c_i))$ , where  $\alpha(w_i; c_i)$  is the semi-arc that originates from the arc  $w_i$  and is incident to the crossing  $c_i$  (see Figure 7). For row relation maps  $f_{\text{row},1}, \ldots, f_{\text{row},m}$ : As  $Q \times Q \to R$ , we define

$$R_{\text{row}}(D,\rho; f_{\text{row},1}, \dots, f_{\text{row},m})$$

$$:= \begin{pmatrix} \operatorname{sgn}(c_1) f_{\text{row},1}(\widetilde{\rho}(r_1), \rho(w_1)) & \cdots & \operatorname{sgn}(c_n) f_{\text{row},1}(\widetilde{\rho}(r_n), \rho(w_n)) \\ \vdots & \ddots & \vdots \\ \operatorname{sgn}(c_1) f_{\text{row},m}(\widetilde{\rho}(r_1), \rho(w_1)) & \cdots & \operatorname{sgn}(c_n) f_{\text{row},m}(\widetilde{\rho}(r_n), \rho(w_n)) \end{pmatrix}.$$

We denote  $R_{\text{row}}(D,\rho; f_{\text{row},1},\ldots,f_{\text{row},m})$  by  $R_{\text{row}}(D,\rho; f_{\text{row}})$  for short. We define

$$\widetilde{R_{\text{row}}}(D,\rho; \boldsymbol{f_{\text{row}}}) := \begin{pmatrix} R_{\text{row}}(D,\rho; \boldsymbol{f_{\text{row}}}) & \boldsymbol{0} \end{pmatrix}.$$

**Definition 6.1.** Let  $a_1, \ldots, a_m \in R$ . Let  $f_{\operatorname{col},i} : Q \to R$  be the column relation map defined by  $f_{\operatorname{col},i}(x) = f_2(x \triangleleft^{-1} a_i, a_i)$ . Let Y be the Q-set  $Q \times R^{\times}$ with  $(y, z) \triangleleft a := (y \triangleleft a, f_1(y, a)z)$ . Let  $f_{\operatorname{row}} : Y \times Q \to R$  be the row relation map defined by  $f_{\operatorname{row}}((y, z), a) = z^{-1}f_1(y, a)^{-1}f_2(y, a)$ . Let  $f_{\operatorname{row},i} : \operatorname{As} Q \times Q \to R$ be the row relation map defined by  $f_{\operatorname{row},i}(y, x) = f_{\operatorname{row}}(\varphi_{a_i}(y), x)$  is a row relation map, where  $\varphi_c : \operatorname{As} Q \to Y$  is the Q-set homomorphism satisfying  $\varphi_c(1) = (c, 1)$ . We then define

$$\Delta(L,\rho; f_1, f_2; a_1, \dots, a_m)$$
  
:=  $\Delta(\widetilde{R_{\text{row}}}(D,\rho; \boldsymbol{f_{\text{row}}}), \widetilde{A}(D,\rho; f_1, f_2), \widetilde{R_{\text{col}}}(D,\rho; \boldsymbol{f_{\text{col}}}))$ 



## 7 Matrices of a diagram with vertices

In this section, we extend the definition of  $A(D, \rho; f_1, f_2)$  to a diagram D with vertices and show that its determinant gives the bracket polynomial.

Let Q be a quandle, and let R be a commutative ring. Let  $(f_1, f_2)$  be an Alexander pair of  $f_1, f_2 : Q \times Q \to R$ . Let D be a diagram of an oriented 1,2,3-valent (n,n)-tangle T, and let  $\rho : \mathcal{A}(D) \to Q$  be a map. Suppose that every component of D has an undercrossing or a vertex. Let  $x_1, \ldots, x_n$  be the arcs of D. We denote by  $c_i$  the initial point of  $x_i$ , which is a crossing or a vertex. We denote by  $y_i$  the arc whose terminal point is  $c_i$ . See the left picture of Figure 6 and Figure 8. We define  $A^{\bullet}(D, \rho; f_1, f_2)$  as the  $n \times n$ matrix whose (i, j)-entry  $a_{ij}^{\bullet}$  is given by

$$a_{ij}^{\bullet} = \begin{cases} -\delta(u_i, x_j) f_1(a_i, b_i) - \delta(v_i, x_j) f_2(a_i, b_i) + \delta(w_i, x_j) \\ & \text{if } c_i \text{ is a positive crossings,} \\ \delta(u_i, x_j) + \delta(v_i, x_j) f_1(a_i, b_i)^{-1} f_2(a_i, b_i) - \delta(w_i, x_j) f_1(a_i, b_i)^{-1} \\ & \text{if } c_i \text{ is a negative crossings,} \\ \delta(x_i, x_j) - \delta(y_i, x_j) & \text{if } c_i \text{ is a bivalent or trivalent vertex,} \\ \delta(x_i, x_j) & \text{if } c_i \text{ is a monovalent vertex,} \end{cases}$$

where  $a_i = \rho(u_i), b_i = \rho(v_i).$ 

**Lemma 7.1.** Let R be a commutative ring. Let  $a_1, ..., a_l \in R, A^{(1)}, ..., A^{(l)} \in M(n, n; R), B, C \in M(m, n; R), D \in M(m, m - n; R)$ . If

$$\sum_{k=1}^{l} \alpha_k = 0 \qquad and \qquad \sum_{k=1}^{l} \alpha_k \left| A_{(i_1,\dots,i_d),(j_1,\dots,j_d)}^{(k)} \right| = 0$$

for any  $d \in \{1, \ldots, n\}$  and any  $i_1, \ldots, i_d, j_1, \ldots, j_d \in \{1, \ldots, n\}$  such that  $1 \leq i_1 < \cdots < i_d \leq n$  and  $1 \leq j_1 < \cdots < j_d \leq n$ , we have

$$\sum_{k=1}^{l} \alpha_k \begin{vmatrix} E_n & -A^{(k)} & O \\ B & C & D \end{vmatrix} = 0,$$

where  $E_n$  is an identity matrix of size n and O is a zero matrix.

We note that  $\sum_{k=1}^{l} \alpha_k A^{(k)} = O$  if and only if  $\sum_{k=1}^{l} \alpha_k \left| A_{(i_1),(j_1)}^{(k)} \right| = 0$  $(1 \leq i_1, j_1 \leq n)$ , since  $\left| A_{(i_1),(j_1)}^{(k)} \right|$  coincides with the  $(i_1, j_1)$ -entry  $a_{i_1, j_1}^{(k)}$  of the matrix  $A^{(k)}$ .

*Proof.* We have

$$\sum_{k=1}^{l} \alpha_k \begin{vmatrix} E_n & -A^{(k)} & O \\ B & C & D \end{vmatrix} = \sum_{k=1}^{l} \alpha_k \begin{vmatrix} E_n & -A^{(k)} & O \\ O & C + BA^{(k)} & D \end{vmatrix}$$
$$= \sum_{k=1}^{l} \alpha_k \left| C + BA^{(k)} & D \right|.$$

Setting  $(\boldsymbol{c}_1 \quad \cdots \quad \boldsymbol{c}_n) := C$  and  $(\boldsymbol{b}_1 \quad \cdots \quad \boldsymbol{b}_n) := B$ , we have

$$\begin{split} &\sum_{k=1}^{l} \alpha_{k} \left| \begin{pmatrix} \boldsymbol{c}_{1} & \cdots & \boldsymbol{c}_{n} \end{pmatrix} + \begin{pmatrix} \boldsymbol{b}_{1} & \cdots & \boldsymbol{b}_{n} \end{pmatrix} \begin{pmatrix} a_{11}^{(k)} & \cdots & a_{1n}^{(k)} \\ \vdots & \ddots & \vdots \\ a_{n1}^{(k)} & \cdots & a_{nn}^{(k)} \end{pmatrix} \right| \\ &= \sum_{k=1}^{l} \alpha_{k} \left| \boldsymbol{c}_{1} + \sum_{i=1}^{n} \boldsymbol{b}_{i} a_{i1}^{(k)} & \cdots & \boldsymbol{c}_{n} + \sum_{i=1}^{n} \boldsymbol{b}_{i} a_{in}^{(k)} & D \right| \\ &= \sum_{k=1}^{l} \alpha_{k} \sum_{d=0}^{n} \sum_{1 \le j_{1} < \cdots < j_{d} \le n} (-1)^{j_{1} + \cdots + j_{d} - \frac{d(d+1)}{2}} \\ & \cdot \left| \sum_{i=1}^{n} \boldsymbol{b}_{i} a_{ij_{1}}^{(k)} & \cdots & \sum_{i=1}^{n} \boldsymbol{b}_{i} a_{ij_{d}}^{(k)} & C_{\widehat{j_{1}, \dots, j_{d}}} & D \right|, \end{split}$$

where  $C_{j_1,\ldots,j_d}$  is the submatrix of C obtained by removing  $j_1,\ldots,j_d$ -th column vectors of C. We then have

$$\sum_{k=1}^{l} \alpha_k \begin{vmatrix} E_n & -A^{(k)} & O \\ B & C & D \end{vmatrix} = 0$$

from the equalities

$$\sum_{k=1}^{l} \alpha_{k} \left| \sum_{i=1}^{n} \boldsymbol{b}_{i} a_{ij_{1}}^{(k)} \cdots \sum_{i=1}^{n} \boldsymbol{b}_{i} a_{ij_{d}}^{(k)} C_{\widehat{j_{1},...,j_{d}}} D \right|$$
  
= 
$$\sum_{1 \leq i_{1} < \cdots < i_{d} \leq n} \sum_{k=1}^{l} \alpha_{k} \left| A_{(i_{1},...,i_{d}),(j_{1},...,j_{d})}^{(k)} \right| \left| \boldsymbol{b}_{i_{1}} \cdots \boldsymbol{b}_{i_{d}} C_{\widehat{j_{1},...,j_{d}}} D \right| = 0,$$

where we note that  $\left| A_{(i_1,...,i_d),(j_1,...,j_d)}^{(k)} \right| = 1$  if d = 0.

**Proposition 7.2.** Let Q be a quandle, and let R be a commutative ring. Let  $(f_1, f_2)$  be an Alexander pair of  $f_1, f_2 : Q \times Q \to R$  satisfying  $f_1(a, b) + f_2(a, b) = 1$  for any  $a, b \in Q$ . Let D be a diagram of an oriented 1, 2, 3-valent (n, n)-tangle T, and let  $\rho : \mathcal{A}(D) \to Q$  be a map. Suppose that every component of D has an undercrossing or a vertex. Let  $\langle (D, \rho) \rangle$  be the bracket polynomial defined in Definition 4.1. Then we have  $\langle (D, \rho) \rangle = |\mathcal{A}^{\bullet}(D, \rho; f_1, f_2)|$ .

*Proof.* We set  $[(D, \rho)] := |A^{\bullet}(D, \rho; f_1, f_2)|.$ 

We have the local relation



from

where we omit common rows and columns. The index  $i_j$  (j = 1, ..., 5) above the determinant indicates the  $i_j$ -th column of the whole matrix and the index  $i_j$  (j = 1, ..., 4) to the left of the determinant indicates the  $i_j$ -th row of the whole matrix. In a similar manner, we have

$$\begin{bmatrix} \mathbf{i} \\ \mathbf{i} \end{bmatrix} = \begin{bmatrix} \mathbf{i} \\ \mathbf{i} \end{bmatrix}, \quad \begin{bmatrix} \mathbf{i} \\ \mathbf{i} \end{bmatrix} = \begin{bmatrix} \mathbf{i} \\$$

,

Let D be an oriented (n, n)-tangle diagram without crossings. If D contains

$$x_i \bigcirc c_i$$
,  $x_i \bigcirc c_i$ ,  $x_i \bigcirc c_i \xrightarrow{} x_j$  or  $x_i \bigcirc c_i \xrightarrow{} x_j$ 

locally, we have  $[(D, \rho)] = 0$ , since the *i*-th row of  $A^{\bullet}(D, \rho; f_1, f_2)$  is the zero vector.

- (i) Suppose that D is a diagram of a cyclic tangle. Since D can be transformed into a diagram containing a loop by using the above local relations, we have  $[(D, \rho)] = 0$ .
- (ii) Suppose that D is a diagram of an acyclic tangle. By using the above local relations, D can be transformed into a collection of simple edges, each of which consists of one edge and two monovalent vertices. We then have

$$[(D, \rho)] = |A^{\bullet}(D, \rho; f_1, f_2)| = |E| = 1,$$

where E is an identity matrix.

Therefore, for an oriented (n, n)-tangle diagram D without crossings, we have

$$[(D, \rho)] = \begin{cases} 1 & \text{if } D \text{ is a diagram of an acyclic tangle,} \\ 0 & \text{if } D \text{ is a diagram of a cyclic tangle.} \end{cases}$$

The equality

$$\begin{bmatrix} x_{i_4} & x_{i_3} \\ a & b \\ b & c \\ x_{i_2} & x_{i_1} \end{bmatrix} = -f_1(a,b) \begin{bmatrix} x_{i_4} & x_{i_3} \\ b \\ b \\ x_{i_2} & x_{i_1} \end{bmatrix} + \begin{bmatrix} x_{i_4} & x_{i_3} \\ b \\ b \\ x_{i_2} & x_{i_1} \end{bmatrix} + f_1(a,b) \begin{bmatrix} x_{i_4} & x_{i_3} \\ a \\ b \\ b \\ x_{i_2} & x_{i_1} \end{bmatrix}$$

follows from

$$\begin{array}{ccccc} i_1 & i_2 & i_3 & i_4 \\ i_1 & \begin{vmatrix} 1 & 0 & -1 + f_1(a,b) & -f_1(a,b) \\ i_2 & \begin{vmatrix} 0 & 1 & -1 & 0 \\ 0 & 1 & -1 & 0 \end{vmatrix} \\ = -f_1(a,b) \begin{vmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & -1 \end{vmatrix} + \begin{vmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & -1 & 0 \end{vmatrix} + f_1(a,b) \begin{vmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & -1 \end{vmatrix},$$

where we omit common rows and columns. By Lemma 7.1, we have this equality from

$$\begin{pmatrix} 1 - f_1(a,b) & f_1(a,b) \\ 1 & 0 \end{pmatrix} = -f_1(a,b) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 1 & 0 \end{pmatrix} + f_1(a,b) \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix}$$

and

$$1 = -f_1(a,b) + 1 + f_1(a,b),$$
  
-f\_1(a,b) = -f\_1(a,b) \cdot 1 + 1 \cdot 0 + f\_1(a,b) \cdot 0.

In a similar manner, we have the equality

$$\begin{bmatrix} x_{i_4} & x_{i_3} \\ b & c \\ a & b \\ x_{i_2} & x_{i_1} \end{bmatrix} = -f_1(a,b)^{-1} \begin{bmatrix} x_{i_4} & x_{i_3} \\ b & c \\ a & x_{i_2} & x_{i_1} \end{bmatrix} + f_1(a,b)^{-1} \begin{bmatrix} x_{i_4} & x_{i_3} \\ b & c \\ a & b \\ x_{i_2} & x_{i_1} \end{bmatrix} + \begin{bmatrix} x_{i_4} & x_{i_3} \\ b & c \\ a & b \\ x_{i_2} & x_{i_1} \end{bmatrix}$$



Figure 9:  $D \to D_{\bullet}$ 

from

$$\begin{array}{cccc} i_1 & i_2 & i_3 & i_4 \\ i_1 & \begin{vmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & -f_1(a,b)^{-1} & -1 + f_1(a,b)^{-1} \end{vmatrix} \\ = -f_1(a,b)^{-1} \begin{vmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & -1 \end{vmatrix} + f_1(a,b)^{-1} \begin{vmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & -1 & 0 \end{vmatrix} + \begin{vmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & -1 \end{vmatrix} .$$

Since  $[(D, \rho)]$  satisfies the defining relations of  $\langle (D, \rho) \rangle$ , we have  $\langle (D, \rho) \rangle = |A^{\bullet}(D, \rho; f_1, f_2)|$ .

Let  $L = K_1 \cup \cdots \cup K_r$  be an oriented *r*-component link, and let  $\rho : Q(L) \to Q$  be a quandle representation. Let *D* be a diagram of *L* such that every component has an undercrossing. We set

$$\begin{split} \widetilde{A^{\bullet}}(D,\rho;f_1,f_2) &:= \begin{pmatrix} A^{\bullet}(D,\rho;f_1,f_2) & \mathbf{0} \\ \mathbf{0} & \left(\prod_{i=1}^r \omega_i^{\frac{\operatorname{rot}(D(K_i)) + \operatorname{wr}(D(K_i)) + 1}{2}}\right)^{-1} \end{pmatrix}, \\ \widetilde{R^{\bullet}_{\operatorname{row}}}(D,\rho;\boldsymbol{f_{\operatorname{row}}}) &:= \left(R^{\bullet}_{\operatorname{row}}(D,\rho;\boldsymbol{f_{\operatorname{row}}}) & \mathbf{0}\right), \end{split}$$

where

$$R^{\bullet}_{\text{row}}(D,\rho; \boldsymbol{f_{\text{row}}})$$

$$:= \begin{pmatrix} -f_{\text{row},1}(\widetilde{\rho}(r(x_1)), \rho(x_1)) & \cdots & -f_{\text{row},1}(\widetilde{\rho}(r(x_n)), \rho(x_n)) \\ \vdots & \ddots & \vdots \\ -f_{\text{row},m}(\widetilde{\rho}(r(x_1)), \rho(x_1)) & \cdots & -f_{\text{row},m}(\widetilde{\rho}(r(x_n)), \rho(x_n)) \end{pmatrix}.$$

Let  $D_{\bullet}$  the diagram obtained from D by adding a bivalent vertex at every crossing as shown in Figure 9. As we see in [8], we have

$$(\widetilde{R_{\text{row}}}(D,\rho; \boldsymbol{f_{\text{row}}}), \widetilde{A}(D,\rho; f_1, f_2), \widetilde{R_{\text{col}}}(D,\rho; \boldsymbol{f_{\text{col}}}))) \sim (\widetilde{R_{\text{row}}}(D,\rho; \boldsymbol{f_{\text{row}}}), \widetilde{A^{\bullet}}(D,\rho; f_1, f_2), \widetilde{R_{\text{col}}}(D,\rho; \boldsymbol{f_{\text{col}}}))) \sim (\widetilde{R_{\text{row}}}(D_{\bullet},\rho; \boldsymbol{f_{\text{row}}}), \widetilde{A^{\bullet}}(D_{\bullet},\rho; f_1, f_2), \widetilde{R_{\text{col}}}(D_{\bullet},\rho; \boldsymbol{f_{\text{col}}})).$$
(7)

Here, we remark that, by using derivatives introduced in [6], we obtain the matrices  $\widetilde{A}(D,\rho;f_1,f_2)$ ,  $\widetilde{A^{\bullet}}(D,\rho;f_1,f_2)$ ,  $\widetilde{A^{\bullet}}(D_{\bullet},\rho;f_1,f_2)$  from the presentations

$$\langle x_1, \dots, x_n \, | \, u_1 \triangleleft v_1 = w_1, \dots, u_n \triangleleft v_n = w_n \rangle, \langle x_1, \dots, x_n \, | \, x_1 = y_1 \triangleleft^{\operatorname{sgn}(c_1)} v_1, \dots, x_n = y_n \triangleleft^{\operatorname{sgn}(c_n)} v_n \rangle, \langle x_1, \dots, x_{2n} \, | \, x_1 = y_1 \triangleleft^{\operatorname{sgn}(c_1)} v_1, \dots, x_{2n} = y_{2n} \triangleleft^{\operatorname{sgn}(c_{2n})} v_{2n} \rangle$$

of the fundamental quandle Q(L), where  $\operatorname{sgn}(c) := 0$  for a bivalent vertex c and  $a \triangleleft^0 b := a$  even if b does not exist.

## 8 The proof of Theorem 1.6

Let p be an odd prime number, and let  $F := \mathbb{Q}(\sqrt{-1})[t]/(t^{p-1}+\cdots+1)$ , which is isomorphic to a cyclotomic field obtained by adjoining a primitive 4pth root of unity to  $\mathbb{Q}$ . We set  $a_1 := 0$ ,  $a_2 := 1 \in F$ . Let  $(f_1, f_2)$  be an Alexander pair of maps  $f_1, f_2 : R_p \times R_p \to F$  defined by  $f_1(a, b) = -t^{b-a}$  and  $f_2(a, b) = t^{b-a} +$ 1. Let  $Y = R_p \times F^{\times}$  be the  $R_p$ -set defined with  $(y, z) \triangleleft a = (2a - y, -t^{a-y}z)$ . We then have the column relation map  $f_{\text{col},1}, f_{\text{col},2} : R_p \to F$  defined by  $f_{\text{col},i}(x) = t^{x-a_i} + 1$  and the row relation map  $f_{\text{row},1}, f_{\text{row},2} : \text{As } Q \times Q \to F$ defined by  $f_{\text{row},i}(y,x) = f_{\text{row}}(\varphi_{a_i}(y),x)$ , where  $f_{\text{row}} : Y \times Q \to F$  is the row relation map defined by  $f_{\text{row}}((y,z),x) = -z^{-1}(t^{y-x}+1)$  and  $\varphi_c : \text{As } Q \to Y$ is the Q-set homomorphism satisfying  $\varphi_c(1) = (c, 1)$ . Let  $L = K_1 \cup \cdots \cup K_r$ be an oriented r-component link, and let  $\rho : Q(L) \to R_p$  be a quandle representation.

Let D be a diagram of an oriented classical (n, n)-tangle T whose closure is L. By Proposition 4.2,

$$(-1)^{-\frac{\operatorname{rot}(D)+\operatorname{wr}(D)}{2}}\langle (D,\rho)\rangle$$

is invariant under the colored Reidemeister moves.

From the local relations

$$\begin{pmatrix} a \\ a \end{pmatrix} = \begin{pmatrix} a \\ a \end{pmatrix} \begin{pmatrix} a \\ a \end{pmatrix} + \begin{pmatrix} a \\ a \end{pmatrix} \begin{pmatrix} a \\ a \end{pmatrix} - \begin{pmatrix} a \\ a \end{pmatrix} \begin{pmatrix} a \\ a \end{pmatrix} ,$$

$$\begin{pmatrix} a \\ a \end{pmatrix} = \begin{pmatrix} a \\ a \end{pmatrix} \begin{pmatrix} a \\ a \end{pmatrix} - \begin{pmatrix} a \\ a \end{pmatrix} \begin{pmatrix} a \\ a \end{pmatrix} + \begin{pmatrix} a \\ a \end{pmatrix} \begin{pmatrix} a \\ a \end{pmatrix} ,$$

we have

$$\Delta_p \begin{pmatrix} a \\ a \end{pmatrix}^a = 2(-1)^{-1/2} \Delta_p \begin{pmatrix} a \\ a \end{pmatrix}^a.$$
(8)



Figure 10:  $\widehat{D}_{\bullet}$ 

Suppose  $\rho$  is trivial. Setting  $X(L,\rho) := (-1)^{r-1} \Delta_p(L,\rho)$ , we have

$$X\left(\bigcirc\right) = 1, \quad X\left(\overset{a}{a} \nearrow \overset{a}{a}\right) - X\left(\overset{a}{a} \nearrow \overset{a}{a}\right) = 2(-1)^{1/2}X\left(\overset{a}{a}\right) \begin{pmatrix} a\\a \end{pmatrix}$$

from (8). Hence we have  $X(L,\rho) = \Delta_L(-1)$ , which implies  $\Delta_p(L,\rho) = (-1)^{r-1} \Delta_L(-1)$ .

Suppose  $\rho$  is nontrivial. Let D be a diagram of an oriented classical (2, 2)tangle T whose closure is L such that the images of  $\rho$  on the top endpoints of D are distinct elements  $a, b \in R_p$ . Suppose that every component of Dhas an undercrossing. Let  $D_{\bullet}$  be the diagram obtained from D by adding a bivalent vertex at every crossing as shown in Figure 9. We denote by  $\widehat{D}_{\bullet}$  the diagram depicted in Figure 10. We note that the diagram obtained from  $\widehat{D}_{\bullet}$ by removing all bivalent vertices represents L. By (7), we have

$$\Delta(L,\rho;f_1,f_2;0,1) = \frac{\det \widehat{A^{\bullet}(D_{\bullet},\rho;f_1,f_2)_{\widehat{2},\widehat{2}}}}{\det \widehat{R^{\bullet}_{\mathrm{row}}}(\widehat{D_{\bullet}},\rho;\boldsymbol{f_{\mathrm{row}}})_{\overline{2},\overline{2}} \det \widehat{R^{\bullet}_{\mathrm{col}}}(\widehat{D_{\bullet}},\rho;\boldsymbol{f_{\mathrm{col}}})_{\overline{2},\overline{2}}},$$

where

$$\begin{split} \widetilde{A^{\bullet}}(\widehat{D_{\bullet}},\rho;f_{1},f_{2})_{\widehat{2},\widehat{2}} &= \begin{pmatrix} A^{\bullet}(D_{\bullet},\rho;f_{1},f_{2}) & \mathbf{0} \\ \mathbf{0} & \prod_{i=1}^{r} (-1)^{-\frac{\operatorname{rot}(\widehat{D_{\bullet}}(K_{i})) + \operatorname{wr}(\widehat{D_{\bullet}}(K_{i})) + 1}{2} \end{pmatrix}, \\ \widetilde{R^{\bullet}_{\operatorname{row}}}(\widehat{D_{\bullet}},\rho;\mathbf{f_{row}})_{\overline{2},\overline{2}} &= \begin{pmatrix} t^{-a} + 1 & -t^{a-b} - t^{-a} \\ t^{1-a} + 1 & -t^{a-b} - t^{1-a} \end{pmatrix}, \\ \widetilde{R^{\bullet}_{\operatorname{col}}}(\widehat{D_{\bullet}},\rho;\mathbf{f_{col}})_{\overline{2},\overline{2}} &= \begin{pmatrix} t^{a} + 1 & t^{a-1} + 1 \\ t^{b} + 1 & t^{b-1} + 1 \end{pmatrix}. \end{split}$$

By Proposition 7.2, we have

$$\det A^{\bullet}(D_{\bullet},\rho;f_1,f_2) = \langle (D_{\bullet},\rho) \rangle = \langle (D,\rho) \rangle.$$

Since

$$\sum_{i=1}^{r} \operatorname{rot}(\widehat{D}_{\bullet}(K_{i})) = \operatorname{rot}(\widehat{D}_{\bullet}) = \operatorname{rot}(D) + 2,$$
$$\sum_{i=1}^{r} \operatorname{wr}(\widehat{D}_{\bullet}(K_{i})) = \operatorname{wr}(\widehat{D}_{\bullet}) - 2\operatorname{lk}(L) = \operatorname{wr}(D) - 2\operatorname{lk}(L),$$

we have

$$\Delta(L,\rho;f_1,f_2;0,1) = \frac{(-1)^{-\frac{\operatorname{rot}(D)+2+\operatorname{wr}(D)-2\operatorname{lk}(L)+r}{2}}\langle (D,\rho)\rangle}{(1-t)(t^{-a}-t^{-b})(1-t^{-1})(t^a-t^b)}$$
$$= \frac{\Delta_p(L,\rho)}{(-1)^{r/2+\operatorname{lk}(L)}(t-2+t^{-1})}.$$

#### The $R_p$ -twisted Alexander invariant 9

In this section, we focus on the  $R_p$ -twisted Alexander invariant and show its properties.

**Lemma 9.1.** For any oriented classical (1, 1)-tangles  $T_1, T_2$ , we have

$$\Delta_p \left( \underbrace{\boxed{T_1}}^a \quad \underbrace{\boxed{T_2}}^a \right) = 0$$

for 
$$a \in R_p$$
.  
Proof. From the skein relation (8), we have  

$$2(-1)^{-1/2}\Delta_p\left(\overbrace{T_1}^a, \overbrace{T_2}^a\right) = \Delta_p\left(\overbrace{T_1}^a, \overbrace{T_2}^a\right) - \Delta_p\left(\overbrace{T_1}^a, \overbrace{T_2}^a\right)$$

$$= 0.$$

Lemma 9.2. We have

$$\left\langle \begin{array}{c} a \\ \vdots \\ a_{n} \end{array} \right\rangle = t^{(b-a)n} \left\langle \begin{array}{c} a \\ a_{n} \end{array} \right\rangle \left\langle \begin{array}{c} b \\ a_{n+1} \end{array} \right\rangle + \frac{1 - t^{(b-a)n}}{1 - t^{b-a}} \left\langle \begin{array}{c} a \\ a_{n} \end{array} \right\rangle \left\langle \begin{array}{c} a \\ a_{n+1} \end{array} \right\rangle$$
$$- t^{b-a} \frac{1 - t^{(b-a)n}}{1 - t^{b-a}} \left\langle \begin{array}{c} a \\ a_{n} \end{array} \right\rangle \left\langle \begin{array}{c} a \\ a_{n+1} \end{array} \right\rangle,$$
$$\left\langle \begin{array}{c} a \\ \vdots \\ a \end{array} \right\rangle \left\langle \begin{array}{c} a \\ a \end{array} \right\rangle \left\langle \begin{array}{c} a \\ a \end{array} \right\rangle \left\langle \begin{array}{c} a \\ a \end{array} \right\rangle + n \left\langle \begin{array}{c} a \\ a \end{array} \right\rangle \left\langle \begin{array}{c} a \\ a \end{array} \right\rangle - n \left\langle \begin{array}{c} a \\ a \end{array} \right\rangle - n \left\langle \begin{array}{c} a \\ a \end{array} \right\rangle \left\langle \begin{array}{c} a \\ a \end{array} \right$$

for  $n \in \mathbb{Z}$  and any distinct elements  $a, b \in R_p$ , where  $a_n = nb - (n-1)a$ .

*Proof.* It is sufficient to show

$$\left\langle \begin{array}{c} a \\ \vdots \\ \vdots \\ \end{array} \right\rangle = x_n \left\langle \begin{array}{c} a \\ \end{array} \right\rangle \left\langle \begin{array}{c} b \\ \end{array} \right\rangle + y_n \left\langle \begin{array}{c} a \\ \end{array} \right\rangle \left\langle \begin{array}{c} b \\ \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ \end{array} \right\rangle \left\langle \begin{array}{c} b \\ \end{array} \right\rangle$$

for any  $n \in \mathbb{Z}$  and  $a, b \in R_p$ , where  $x_n = t^{(b-a)n}$  and

$$y_n = \begin{cases} \sum_{i=0}^{n-1} t^{(b-a)i} & \text{if } n > 0, \\ 0 & \text{if } n = 0, \\ -\sum_{i=n}^{-1} t^{(b-a)i} & \text{if } n < 0, \end{cases} \qquad z_n = \begin{cases} -\sum_{i=1}^n t^{(b-a)i} & \text{if } n > 0, \\ 0 & \text{if } n = 0, \\ \sum_{i=n+1}^0 t^{(b-a)i} & \text{if } n < 0. \end{cases}$$

We have the equality by induction on n from the equalities

$$\left\langle \begin{array}{c} a \\ \vdots \\ a_{n+1} \end{array} \right\rangle = x_n \left\langle \begin{array}{c} a \\ a_{n+1} \end{array} \right\rangle = x_n \left\langle \begin{array}{c} a \\ a_{n+1} \end{array} \right\rangle = x_n \left\langle \begin{array}{c} a \\ a_{n+1} \end{array} \right\rangle + y_n \left\langle \begin{array}{c} a \\ a_{n} \end{array} \right\rangle = x_n \left\langle \begin{array}{c} a \\ a_{n+1} \end{array} \right\rangle + y_n \left\langle \begin{array}{c} a \\ a_{n+1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n+1} \end{array} \right\rangle = x_n \left\langle \begin{array}{c} a \\ a_{n+1} \end{array} \right\rangle = t^{b-a} x_n \left\langle \begin{array}{c} a \\ a \\ \end{array} \right\rangle \left\langle \begin{array}{c} b \\ b \end{array} \right\rangle + (y_n + x_n) \left\langle \begin{array}{c} a \\ a \\ \end{array} \right\rangle \left\langle \begin{array}{c} b \\ b \end{array} \right\rangle + (z_n - t^{b-a} x_n) \left\langle \begin{array}{c} a \\ a \\ \end{array} \right\rangle \left\langle \begin{array}{c} a \\ b \\ \end{array} \right\rangle$$
$$= x_{n+1} \left\langle \begin{array}{c} a \\ a \\ \end{array} \right\rangle \left\langle \begin{array}{c} b \\ b \\ \end{array} \right\rangle + y_{n+1} \left\langle \begin{array}{c} a \\ a \\ \end{array} \right\rangle \left\langle \begin{array}{c} b \\ b \\ \end{array} \right\rangle + z_{n+1} \left\langle \begin{array}{c} a \\ a \\ \end{array} \right\rangle \left\langle \begin{array}{c} a \\ b \\ \end{array} \right\rangle$$

for  $n \ge 0$  and the equalities

$$\left\langle \begin{array}{c} a \\ \vdots \\ a_{n-1} \end{array} \right\rangle = \left\langle \begin{array}{c} a \\ \vdots \\ a_{n-1} \end{array} \right\rangle = \left\langle \begin{array}{c} a \\ \vdots \\ a_{n-1} \end{array} \right\rangle = n+1 \right\rangle$$

$$= x_n \left\langle \begin{array}{c} a \\ a_n \\ a_{n+1} \end{array} \right\rangle + y_n \left\langle \begin{array}{c} a \\ a_n \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_n \\ a_{n-1} \end{array} \right\rangle = x_n \left\langle \begin{array}{c} a \\ a_n \\ a_{n-1} \end{array} \right\rangle + y_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle = x_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + y_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle = x_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + y_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle = x_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + y_{n-1} \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_{n-1} \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a \\ a_{n-1} \end{array} \right\rangle + z_n \left\langle \begin{array}{c} a$$

for  $n \leq 0$ .

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Proof of Proposition 1.7. By Lemma 9.2, we have

which imply the skein relations.

By the definition of  $\Delta_p(L,\rho)$ , we have

$$\Delta_p \left( \bigcirc b \right) = \left\langle \left| a \right\rangle = 1,$$
  
$$\Delta_p \left( \bigcirc b \right) = \frac{1}{(t^a - t^b)(t^{-a} - t^{-b})} \left\langle a \right| \quad \left| b \right\rangle = \frac{1}{(t^a - t^b)(t^{-a} - t^{-b})}$$

for any distinct elements  $a, b \in \mathbb{R}_p$ . By Lemma 9.1, we have

$$\Delta_p\left(\bigcirc a & a \\ \bigcirc & \bigcirc \right) = 0, \qquad \Delta_p\left(\bigcirc a_1 & a_r \\ \bigcirc & \bigcirc \\ \bigcirc & \bigcirc \\ \end{pmatrix} = 0$$

for any  $r \geq 3$  and  $a, a_1, \ldots, a_r \in R_p$  such that  $a_1 = a_2$ . Suppose  $a_1 \neq a_2$ . We have

where  $a'_1 = 2a_2 - a_1$  and  $a'_2 = 3a_2 - 2a_1$ . Repeating this procedure, we have the colors

$$a_1, a_2, 2a_2 - a_1, 3a_2 - 2a_1, \dots, (p-1)a_2 - (p-2)a_1$$

Since these elements are mutually distinct, one of them coincides with  $a_3$ . Hence, we have  $a_1 = a_r$ 

for any  $r \geq 3$  and  $a_1, \ldots, a_r \in R_p$ .

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