

### Third terms of lens surgery polynomial

2020年4月8日 17:33

$K \subset S^3$  lens space knot surgery slope  
 iff  $\exists p > 0$  s.t.  $S^3_p(K) = L(p, q)$

$\Delta(t)$  is lens surgery polynomial  
 iff  $\exists$  lens space knot  $K$  s.t.  $\Delta_K(t) = \Delta(t)$

Question 1 When is a polynomial  $\Delta(t)$  a lens surgery polynomial?

Here we write the coeff of  $\Delta_K(t)$  ( $d=g$ )

$$\Delta_K = a_g t^g + a_{g-1} t^{g-1} + \dots + a_{g+1} t^{-g+1} + a_g t^{-g}$$

where  $a_i = a_{-i}$ ,  $\Delta_K(1) = 1$

Fact 2 (Oszvath-Szabo).  $K \subset S^3$  is a lens space knot.

Then  $\Delta_K(t)$  is the following form.

$$\Delta_K = (-1)^m + \sum_{j=1}^m (-1)^{j-1} (t^{n_j} + t^{-n_j})$$

$$d = n_1 > n_2 > \dots > n_{m-1} > 0$$

$\left\{ \begin{array}{l} \text{flat} : f(t) \quad \forall \text{ coeff } a_i \quad |a_i| \leq 1 \\ \text{alternating: } a_0, a_1, \dots, a_g : \text{ non zero seq in order} \\ \quad \quad \quad a_i = (-1)^i \end{array} \right.$

Fact 3 (Oszvath-Szabo)  $K \subset S^3$  is a lens space knot

$p$ : the surgery slope.

Then,  $2g-1 \leq p$ .

Fact 4 (T. Hedden-Watson)  $K \subset S^3$  is a l. sp knot

Fact 4 (T. Hedden-Watson)  $K \subset S^3$  is a l. sp knot

$$\Delta_K(t) = t^g - t^{g-1} + \dots$$

( c.f HW proved for any L-space knot  
the same statement. )

Question 5 (Teragaito) If a surg poly  $\Delta(t)$

$$\text{is } \Delta(t) = t^g - t^{g-1} + t^{g-2} - \dots$$

$$\begin{aligned} \text{then } \Delta(t) &= t^g - t^{g-1} + t^{g-2} - \dots - t^{-g+1} + t^{-g} \\ &= \Delta_{T(2,2g+1)}(t) ? \end{aligned}$$

Then,

$\Delta$ : lens surgery polynomial

$$\text{not } \Delta = t^g - t^{g-1} + t^{g-2} - \dots - t^{-g}$$

$$\text{then } a_{g-2} = 0$$

Main theorem 6  $K \subset S^3$  is a lens sp. knot  
then Teragaito's question is true

To prove the main thm. we prepare  
the following infinite matrix.  $(A_{ij})$

$Y: \mathbb{Z}HS^3$ .  $K \subset Y$  lens sp. knot.

$$Y_p(K) = L(p, g) \supset \tilde{K} \quad [\tilde{K}] \in H_1(L(p, g)) = \mathbb{Z}/p\mathbb{Z}$$

$$C \subset L(p, g)$$

$$\begin{array}{c} \text{H}_0 \quad \text{H}_1 \\ \text{C} \end{array} \cup \text{C} = \langle [c] \rangle$$

$$[\tilde{K}] = k[C]$$

$(p, k)$ . lens surgery  
parameter

$\phi$  lens surgery  
parameter  
 dual class.

$[\alpha]_p$ : the least absolute remainder.  
 when dividing by  $p$ .

$$-\frac{p}{2} < [\alpha]_p \leq \frac{p}{2}$$

$$k_2 := |[\kappa^{-1}]_p|$$

constant

$$\cdot e \equiv k k_2 \pmod{p}; \quad e = \pm 1$$

$$\cdot c = \frac{(k-1)(k+1-p)}{2}$$

$$\cdot m = \frac{k k_2 - e}{p}$$

$$\cdot I_\alpha = \begin{cases} \{1, 2, \dots, \alpha\} & \alpha > 0 \\ \{\alpha+1, \alpha+2, \dots, -1, 0\} & \alpha < 0 \end{cases}$$

$$\cdot \mathfrak{g} = [\mathfrak{k}^2]_p, \quad \mathfrak{g}_2 = [\mathfrak{k}_2^2]_p$$

Prop 7  $K$ : lens sp. knot in  $S^3$ .

$$\Upsilon_p(K) = L(p, \mathfrak{g})$$

$$\alpha_i = -em + e \cdot \#\{j \in I_k \mid [\mathfrak{g}_2(j+ki+c)]_p \in I_{ek_2}\}$$

then

$$a_i = \alpha_i \quad |i| \leq g.$$

Actually.  $a_i = \alpha_i \quad |i| \leq p/2.$

$$\bar{a}_i = a_{[i]_p}. \quad (\text{periodic extension})$$

$$\begin{aligned}
 A_{i,j} &= \overline{a}_{k_2(i-c)+j} \\
 &= \overline{a}_{k_2(x-c)} \\
 &= A(x)
 \end{aligned}$$

$$m = \frac{kb_2 - e}{p}$$

Example 8  $x=0$  ( $i=j=0$ )

$$m' = \frac{ekb_2 - 1}{p}$$

$$A(0) = \overline{a}_{-k_2c} = \overline{a}_{-ekb_2c}$$

$$= -e(m - \#\{j \in I_b \mid [\delta_2(j+k(-ekb_2c)+c)]_p \in I_{ekb_2}\})$$

$$= -e(m - \#\{j \in I_b \mid [\delta_2 j]_p \in I_{ekb_2}\})$$

$$\left( \begin{aligned}
 &= -e(m - (k - \#\{j \in I_k \mid [\delta_2 j]_p \in I_{k_2}\})) \quad (e=-1) \\
 &= -e(m - k + \#\{j \in I_k \mid [\delta_2 j]_p \in I_{p-k_2}\}) \\
 &= -m' + \#\{j \in I_k \mid [\delta_2 j]_p \in I_{p-k_2}\}
 \end{aligned} \right)$$

where  $[\alpha]_p$  the remainder among  $\{1, 2, \dots, p\}$

$$m' = \begin{cases} \frac{kb_2 - 1}{p} & e=1 \\ \frac{k(p-k_2) - 1}{p} & e=-1 \end{cases} = \frac{kb' - 1}{p}$$

$$k' = [k]_p$$

$$\therefore A(0) = -m' + \#\{j \in I_k \mid [\delta_2 j]_p \in I_{k'}\}$$

$$= -m' + \Phi(k) \quad \text{Salto's } \Phi$$

$$A(-1) = \overline{a}_{ekb_2(-1-c)} = -m' + \#\{j \in I_k \mid [\delta_2(j-1)]_p \in I_{k'}\}$$

$$= -m' + \#\{j \in I_{k-1} \mid [\delta_2 j]_p \in I_{k'}\}$$

$$= -m' + \#\{j \in I_k \mid [\delta_2 j]_p \in I_{k'}\}$$

$$= -m' + \Phi(0) - 1$$

$$= A(0) - 1$$

by O-S condition. (Fact 1)

$$(A(0), A(-1)) = (1, 0), (0, -1)$$

$$\therefore -m' + \Phi(k) = 1 \text{ or } 0$$

multiplying by  $p$

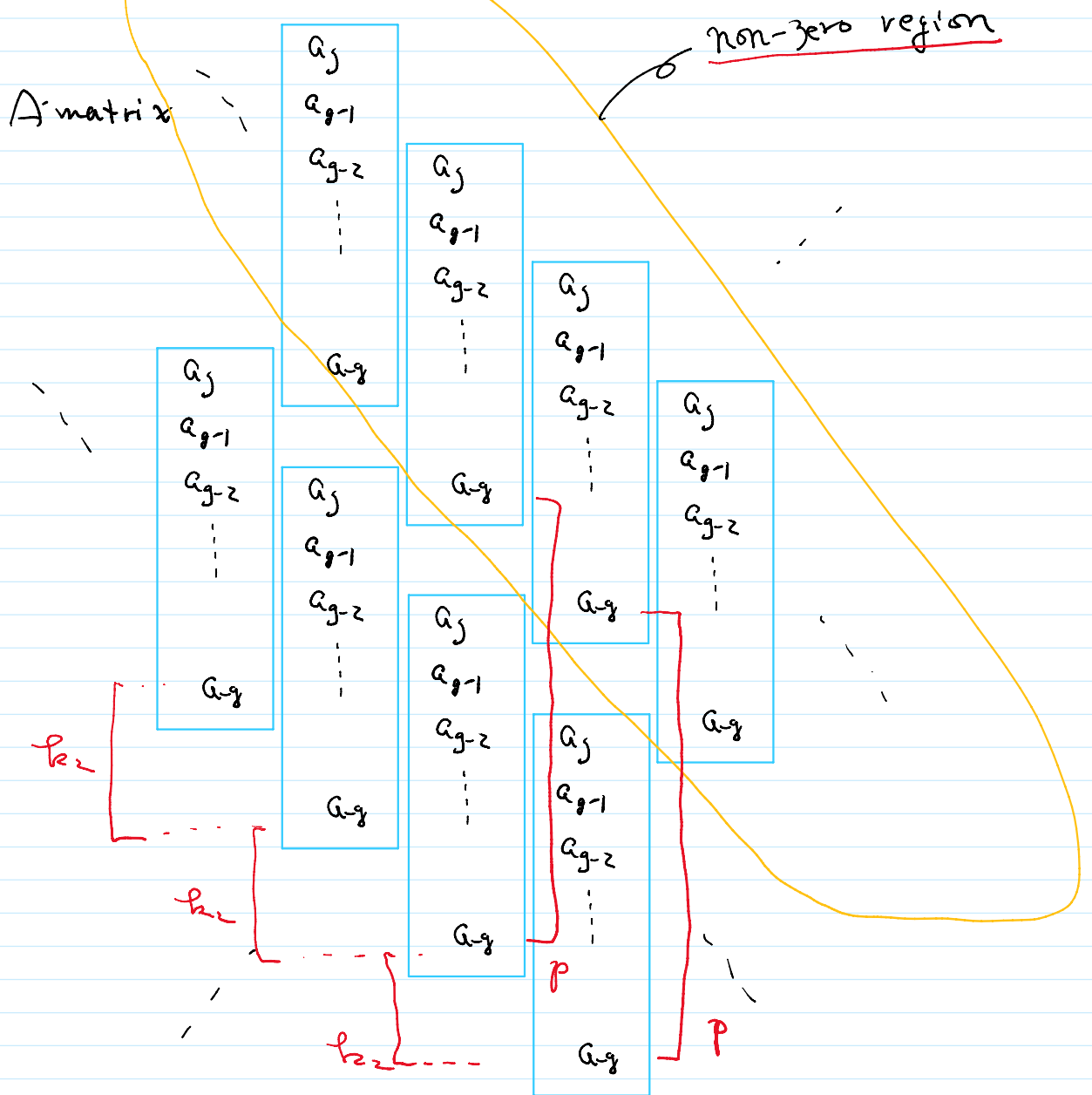
$$1 - kb' + p\Phi(k) = p \text{ or } 0$$

multiplying by  $p$

$$1 - kb' + p\bar{\Phi}(k) = p \quad \text{or} \quad 0$$

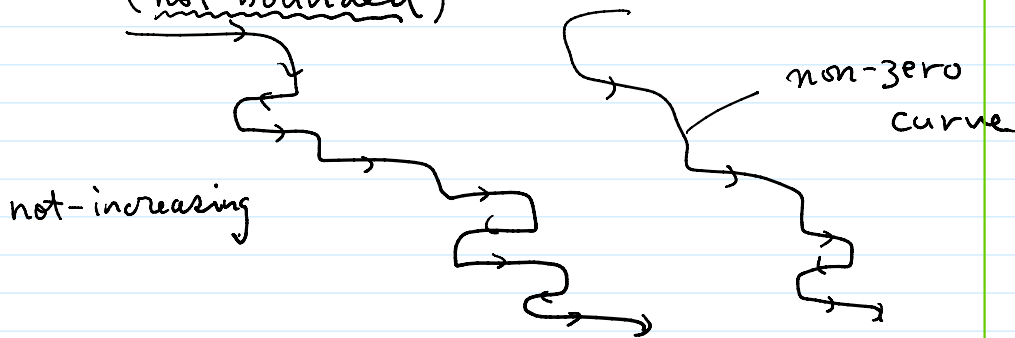
$$-p\bar{\Phi}(k) + kb' = -p + 1 \quad \text{or} \quad -1$$

(Saito's condition)



Prop 9  $\forall$  A-matrix

$\exists$  an oriented curve in  $\mathbb{R}^2$   
 (not bounded)



s.t.  $\rightarrow \dots \rightarrow = 1 \ 1 \dots 1 \ 1$

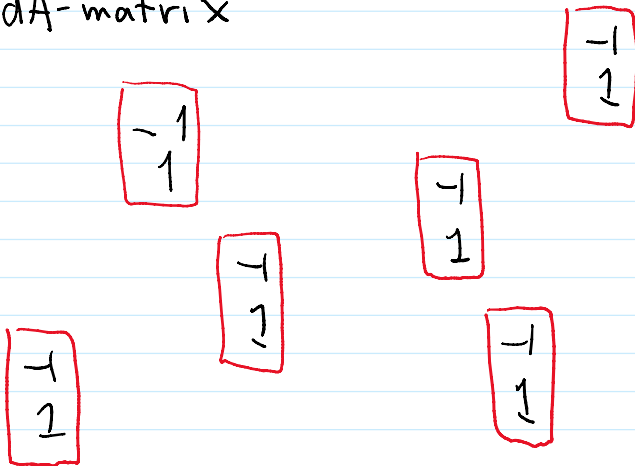
$\leftarrow \leftarrow = -1 \ -1 \dots -1 \ -1$

$\dots \begin{matrix} \rightarrow \\ \leftarrow \end{matrix} = \dots \begin{matrix} 1 & 1 \\ -1 & -1 \end{matrix}$

$\phi = \begin{matrix} 0 & \dots & 0 \\ 0 & \dots & 0 \\ \vdots & & \vdots \\ 0 & \dots & 0 \end{matrix}$

$dA_{ij} = A_{i,j} - A_{i-1,j}$

dA-matrix



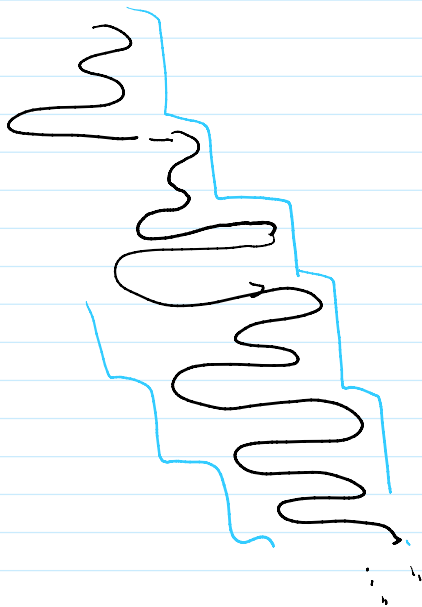
Lem 10 A-matrix of a lens sp. knot.  
 there exists  $m \geq 0$ , s.t.

$dA$ .

$$\begin{array}{c} \boxed{-1} \\ \boxed{1} \\ \vdots \\ \vdots \\ \boxed{-1} \\ \boxed{1} \end{array} \left. \vphantom{\begin{array}{c} \boxed{-1} \\ \boxed{1} \\ \vdots \\ \vdots \\ \boxed{-1} \\ \boxed{1} \end{array}} \right\} m \text{ a } m+1$$

Prop 11 In each non-zero region  
 for any A-matrix.

there is one comp non-zero  
 curve only.



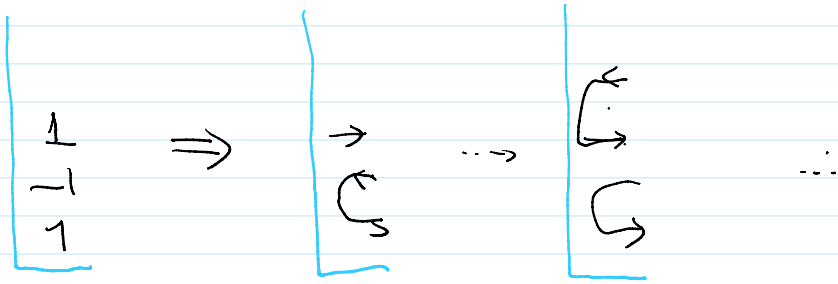
### Proof of Theorem 6

$K \subset S^3$  lens sp. knot

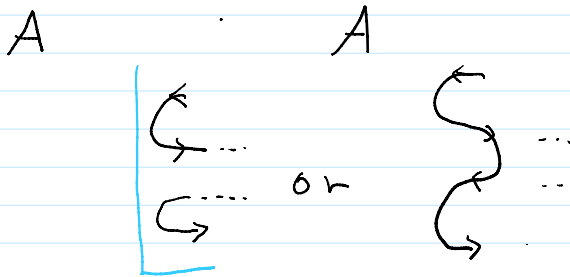
Suppose  $\Delta_r(t) = t^g - t^{g-1} + t^{g-2} - \dots$

$K \subset \mathbb{C}$  low sp. char

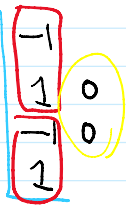
Suppose  $\Delta_k(t) = t^g - t^{g-1} + t^{g-2} - \dots$



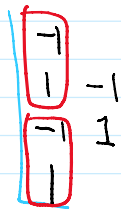
$\Delta_k = t^g - t^{g-1} + t^{g-2} - t^{g-3} + \dots$



Case I  
dA



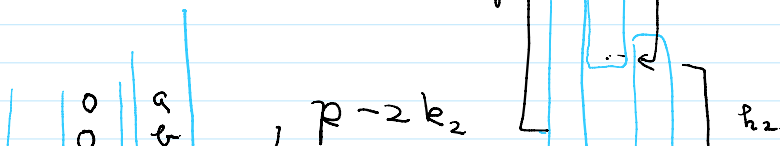
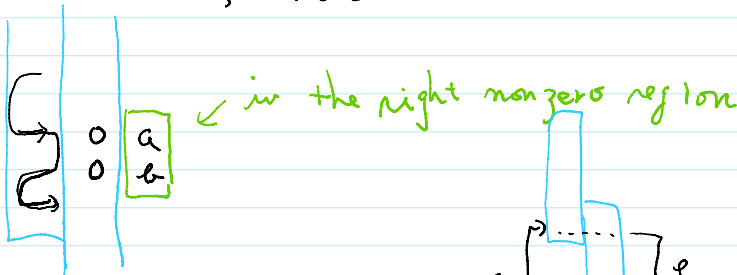
Case II  
dA



Contradiction  
to Lemma. 10

★

★ If  $ab=0$ , then





$$\left[ \begin{array}{c|c|c} 1 & 0 & g \\ & 0 & g \\ & \dots & \dots \end{array} \right] \xrightarrow{p-2k_2} \left[ \begin{array}{c|c|c} 1 & 0 & g \\ & 0 & g \\ & \dots & \dots \end{array} \right]_{k_2}$$

$$\therefore p-2k_2 \leq 2.$$

$$\text{by } 2k_2 < p$$

$$(k_2, 2) = 1$$

$$\therefore p-2k_2 = 2 \text{ or } 1.$$

$$k_2 = 2k+1$$

$$\therefore p = \underline{2k_2+2} \text{ or } \underline{2k_2+1}.$$

$$4k+3 = p$$

$$\hookrightarrow k=2.$$

$$(k_2, 2) = 1$$

$$k_2^2 - 1 = \frac{k_2-1}{2}(2k_2+2) \equiv 0 \pmod{p}$$

$$\therefore g_2 = 1 \quad \text{a surgery yielding } L(p, 1)$$

Here we use this classification

$$\rightsquigarrow k_2 = 1 \quad \text{KMOS.}$$

Thm 11(T)  $K \subset Y$ : a lens sp. knot

$$Y_p(K) = L(p, g) \text{ with } (p, k)$$

the following conditions are equivalent

- 1)  $(p, k)$  is realized by  $(2, 2g+1)$
- 2)  $k=2$
- 3)  $k_2 = 2g+1$  or  $2g$
- 4)  $\Delta_K(t) = \Delta_{T(2, 2g+1)}(t)$

If  $A$  satisfies

$$\left[ \begin{array}{c|c|c} 1 & 0 & 0 \\ & 0 & 0 \\ & \dots & \dots \end{array} \right]$$

then

$$dA \left[ \begin{array}{c|c|c} -1 & 0 & 0 \\ & 1 & 0 \\ & -1 & 0 \\ & 1 & 0 \end{array} \right]$$

contradiction  
to Lemma (D)

Therefore such a surgery is realized by

$$T(2, 2g+1)$$

$$\text{In particular, } \Delta_K = \Delta_{T(2, 2g+1)} //$$

Cor 12  $K \subset S^3$  a lens sp. knot

with  $\Delta_K = \Delta_{T(2,2g+1)}$

then any lens surg. parameter  $(p, k)$

of  $K$ . (i.e.  $S^3_p(K) = L(p, \varepsilon)$   
para.  $(p, k)$ )

is realized by  $T(2, 2g+1)$   
for some integer  $g$ .

$(p, k)$  is realized by a knot  $K \subset Y$

$Y_p(K) = L(p, \varepsilon)$  has the parameter  
 $(p, k)$

§2.  $K_{p, k} \subset Y_{p, k}$

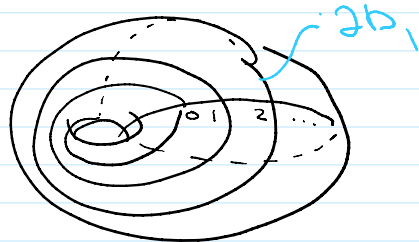
$(p, k)$  relatively prime

$Y_{p, k} \cong H \# S^3$   $K_{p, k} \subset Y_{p, k}$

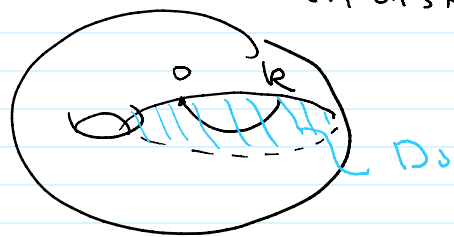
$(Y_{p, k})_p(K_{p, k}) = L(p, k^2) \supset \tilde{K}_{p, k}$

$H_0 \cup_2 H_1$

$H_i \supset D_i$   
men disk.



$H_0$



$H_0$

Question 13 Any  $K_{p, k}$  is

$$\Delta_{K_{p, k}} = t^g - t^{g-1} + t^{g-2} \dots$$

then

$$K_{p, k} = T(2, 2g+1)$$